Modelling the hidden magnetic field of low-mass stars

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ABSTRACT
Zeeman–Doppler imaging is a spectropolarimetric technique that is used to map the large-scale surface magnetic fields of stars. These maps in turn are used to study the structure of the stars’ coronae and winds. This method, however, misses any small-scale magnetic flux whose polarization signatures cancel out. Measurements of Zeeman broadening show that a large percentage of the surface magnetic flux may be neglected in this way. In this paper we assess the impact of this ‘missing flux’ on the predicted coronal structure and the possible rates of spin-down due to the stellar wind. To do this we create a model for the small-scale field and add this to the Zeeman–Doppler maps of the magnetic fields of a sample of 12 M dwarfs. We extrapolate this combined field and determine the structure of a hydrostatic, isothermal corona. The addition of small-scale surface field produces a carpet of low-lying magnetic loops that covers most of the surface, including the stellar equivalent of solar ‘coronal holes’ where the large-scale field is opened up by the stellar wind and hence would be X-ray dark. We show that the trend of the X-ray emission measure with rotation rate (the so-called ‘activity–rotation relation’) is unaffected by the addition of small-scale field, when scaled with respect to the large-scale field of each star. The addition of small-scale field increases the surface flux; however, the large-scale open flux that governs the loss of mass and angular momentum in the wind remains unaffected. We conclude that spin-down times and mass-loss rates calculated from surface magnetograms are unlikely to be significantly influenced by the neglect of small-scale field.

Key words: stars: activity – stars: coronae – stars: low-mass – stars: magnetic field – X-rays: stars.

1 INTRODUCTION
M dwarfs, much smaller, dimmer and cooler than stars like our Sun, are by far the most common type of star in our Galaxy. The study of these stars has remained limited due to their faintness and in the past it was presumed that M dwarfs were unlikely to host detectable habitable planets. More recently however, the advantages of searching for habitable planets around M dwarfs have been recognized. For example, the habitable zone is closer and so it is easier to find planets by radial velocity searches. Despite the advantages of detecting planets around these stars, M dwarfs have been shown to be extremely magnetically active which may have significant effects on any planetary system. For example, intense magnetic fields, stellar flares, ultraviolet (UV) and X-ray emission and the powerful stellar winds (Vidotto et al. 2013) may affect planetary atmospheres as well as any potential organisms on these planets. This makes it vital to investigate how the structure and evolution of the magnetic field, both large-scale and small-scale, can affect coronal properties.

Time-resolved spectropolarimetric observations of a star can be analysed by means of Zeeman–Doppler imaging (ZDI; Semel 1989; Donati et al. 2006b) in order to reconstruct a map of the vector magnetic field on the stellar surface. ZDI relies on the fact that due to the combination of the properties of the Zeeman effect, e.g. rotation-induced Doppler and rotational modulation, a strong relation exists between the distribution of the magnetic field at the surface of a star and the rotational evolution of polarization in spectral lines during a stellar rotation. However, several limitations exist: in particular, with the solution being non-unique, a maximum entropy criterion has to be used, and due to the mutual cancellation of polarized signals originating from neighbouring regions of opposite polarities, the maps have a limited spatial resolution and, therefore, systematically

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miss magnetic flux corresponding to magnetic fields organized on small spatial scales. The actual resolution is mostly driven by the rotational velocity of the star projected on the observer’s line-of-sight ($v\sin i$): the higher the $v\sin i$, the higher the resolution. In addition, for the inclination of the stellar rotation axis with respect to the line-of-sight differing from 90°, a part of the star is never visible. Therefore, in that region there is no constraint on the magnetic field, except that globally it has to satisfy the null-divergence constraint.

Studies based on spectropolarimetric observations and ZDI have provided the first information on the structure of the surface magnetic fields of M dwarfs. In particular, partly convective M dwarfs have been shown to host large-scale magnetic fields which are non-axisymmetric and feature a strong toroidal component (Donati et al. 2008), whereas those close to the limit of full convection have been shown to host much stronger large-scale field dominated by a mainly axisymmetric poloidal component (e.g. Donati et al. 2006a; Morin et al. 2008a,b). However, these studies do not constrain the small-scale field component of the magnetic fields of low-mass stars. In parallel, studies based on the analysis of the Zeeman broadening in unpolarized spectra have provided complementary information: the measure of the disc-averaged magnetic field including the contributions of both the large-scale and small-scale components. Reiners & Basri (2009) compiled measurements of mean magnetic flux from Stokes $I$ (total intensity) and Stokes $V$ (the fractional degree of circular polarization) parameters for a selection of partially convective and fully convective M dwarfs. They find that the fraction of magnetic flux visible in Stokes $V$ is a small percentage of the total flux measured in Stokes $I$. This means that a large portion of the magnetic flux stored in magnetic fields is invisible to Stokes $V$. One possible explanation is that the majority of magnetic flux on M dwarfs is grouped into small structures distributed over the stellar surface, where different polarities cancel each other out in Stokes $V$. More specifically, Reiners & Basri (2009) find that although for the lower mass fully convective stars, the mean magnetic flux does not significantly differ from partially convective stars (Reiners & Basri 2007), the fraction of the total magnetic flux detected in Stokes $V$ is different for partially convective and fully convective stars: 6 and 14 per cent, respectively.

The aim of this paper is to determine the influence that this small-scale field has on the structure of the surface magnetic fields of M dwarfs, in particular, for partly convective M dwarfs. We (1) fix the value of $B_{\text{max}}$, taking into account in ZDI for our sample of partly convective and fully convective M Dwarfs, we (1) fix the value of $B_{\text{max}}$ to be either ±500 G or ±1000 G; and (2) set the value of $B_{\text{max}}$ such that the large-scale field contributes between approximately 6 and 14 per cent of the total field, respectively, as indicated in Reiners & Basri (2009). The values for the average radial flux in each case can be found in Table 1.

To ensure the small-scale field is evenly distributed over the entire surface of the star, we keep the spot coverage constant. We, therefore, find that an appropriate parameter to vary in the model is $B_{\text{max}}$. To ensure that the model is valid within the uncertainties of the data, we (1) fix the value of $B_{\text{max}}$ to be either ±500 G or ±1000 G; and (2) set the value of $B_{\text{max}}$ such that the large-scale field contributes between approximately 6 and 14 per cent of the total field, respectively, as indicated in Reiners & Basri (2009). The values for the average radial flux in each case can be found in Table 1.

The spots were created using the Doppler imaging code ‘Doppler Tomography of Stars’ (DoTS) and all spots were modelled, following Solanki (1999), with circular umbra areas and a ratio of umbral to penumbral area of 1:3.

We use the spot brightness to allocate field strengths to the centre of the active regions and allow the field strength to fall-off in a Gaussian-like distribution, to the edge of each spot, i.e.

$$B_r^i = \frac{B_{\text{max}}}{\Sigma_{\text{brightness}}} e^{-\frac{r^2}{\Sigma_{\text{brightness}}^2}},$$

(1)

where $B_r^{\text{vis}}$ represents the field strength in the small-scale field, $\Sigma_{\text{brightness}}$ is the spot brightness, $B_{\text{max}}$ is the arbitrarily chosen maximum field strength and $x$ is the distance from the centre of the spot.

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The surface magnetic radial map for the small-scale field is shown in Fig. 1 where the spot distribution covers approximately 62 per cent of a model star. Fig. 1 represents the case where $B_{\text{max}} = 500$ G. The simulated magnetic radial maps for the small-scale field are added to the reconstructed radial maps obtained through ZDI and new surface maps with both large-scale and small-scale field are created for each M dwarf, i.e. $B_{\text{total}} = B_r^{\text{vis}} + B_r^c$.

### 2.2 The coronal field

The magnetic field is extrapolated above the stellar surface using the potential field source surface (PFSS) method (Altschuler & Newkirk 1969), where the magnetic field is assumed to be current free ($\nabla \times B = 0$) and divergence free ($\nabla \cdot B = 0$). In a format similar to Jardine et al. (1999) the components of the coronal magnetic field are determined from the solution to Laplace’s equation $\nabla^2 \psi = 0$, where $\psi$ is the scalar potential:

$$B_r = -\sum_{l=1}^{N} \sum_{m=1}^{l} \left[ a_{lm} r^{-l-1} - (l + 1) b_{lm} r^{-(l+2)} \right] P_{lm}(\cos \theta) e^{im\phi},$$

(2)

$$B_\theta = -\sum_{l=1}^{N} \sum_{m=1}^{l} \left[ a_{lm} r^{-l-1} + b_{lm} r^{-(l+2)} \right] \frac{d}{d\theta} P_{lm}(\cos \theta) e^{im\phi},$$

(3)

$$B_\phi = -\sum_{l=1}^{N} \sum_{m=1}^{l} \left[ c_{lm} r^{-l-1} + d_{lm} r^{-(l+2)} \right] P_{lm}(\cos \theta) \frac{im}{\sin \theta} e^{im\phi},$$

(4)
associated Legendre polynomials, $\text{alm}$, the spherical harmonics, $\text{l}$, \text{MNRAS} 439, conditions. The upper condition is that at the source surface, $R$, $B_r$ (with $B_r$ representing the radial magnetic field component). Colours are scaled to the maximum and minimum values of the surface radial magnetic field component.

### 2.3 X-ray emission model

The structure of the magnetic field is influenced by the strength of the surface field and the distribution of plasma. Following the model in Lang et al. (2012), the density structure can be estimated for the extrapolated corona by assuming the plasma is hydrostatic and isothermal and that the gas pressure at the stellar surface is proportional to the magnetic pressure ($p_o = \kappa \frac{B^2}{\mu}$), $\kappa$ is a constant of proportionality relating the base gas pressure $p_o$ to magnetic pressure $B_o$ through the magnetic constant $2\mu$. The value of $\kappa$ is chosen such that the coronal densities lie within the observed range for M dwarfs, $10^9$–$10^{12}$ cm$^{-3}$ (Ness et al. 2002, 2004). Typical values for $\log \kappa = [-5: -7]$. 

![Figure 1. Radial magnetic surface map for the model of small-scale field covering 62 per cent of the stellar surface. $|B_{\text{max}}|$ is 500 G with an unsigned surface flux value $\phi_{\text{surface}} \approx 10^{24}$ Mx.](image1)

![Figure 2. 3D coronal extrapolation of the small-scale field shown in Fig. 1. Colours are scaled to the maximum and minimum values of the surface radial magnetic field component.](image2)
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We assume that the pressure varies along each field line according to
\[ p = p_{\text{eq}} e^{-\frac{\mu B_{\text{ls}}}{k_{\text{B}} T}}, \]
where \( r = R/R_\star \) and the ratios of centrifugal (\( \phi_c \)) and gravitational (\( \phi_g \)) to thermal energy are given by
\[ \phi_c = m_e \left( \frac{\omega R_\star^2}{k_{\text{B}} T} \right), \]
\[ \phi_g = m_e \left( \frac{G M_\star}{R_\star k_{\text{B}} T} \right), \]
where \( R_\star \) is the stellar radius, \( M_\star \) is the stellar mass, \( \omega \) is the stellar rotation rate, \( k_{\text{B}} \) is the Boltzmann constant, \( G \) is the gravitational constant and \( m_e \) is the electron mass.

To ensure that only regions of the closed stellar corona contribute towards the emission measure, the gas pressure along open field lines is taken to be zero. In addition to this, if there is any overpressure along the designated closed loops, i.e. gas pressure \( (p = 2n_e k T) \geq \) magnetic pressure \( (p_B = B^2/2\mu) \), then the pressure at that grid point is also set to zero.

Assuming the gas is optically thin, the X-ray emission measure varies with density, i.e.
\[ \text{EM}(r) = \int n_e^2 dV. \]

The temperature \((T = 2 \times 10^6 \text{ K})\), source surface \((R_{\text{ss}} = 2.5R_\star)\) and constant of proportionality \( \kappa \) \((10^{-6})\) are kept constant in this paper (for more details see Lang et al. 2012).

3 RESULTS

3.1 Field structure

With the addition of small-scale field B drops more rapidly with height, close to the stellar surface. As such, we do not find any great change in the large-scale field structure. This is evident from Fig. 3 which shows the radial field at both the stellar surface and the source surface. Figs 3(a) and (c) which represent the large-scale and large-scale+small-scale field at the stellar surface, respectively, show very different topologies; however, when this is extrapolated out to the source surface (Figs 3b and d) the topologies are similar. We conclude from this that the magnetic pressure falls off with radius more quickly with the addition of small-scale field leaving only the large-scale components near the source surface.

Fig. 4 shows the coronal magnetic field of (1) the large-scale field extrapolated from the reconstructed radial maps (left-hand column); and (2) the large-scale+small-scale field, where the small-scale field is scaled according to Reiners & Basri (2009), such that \( B_{\text{ls}} = 6 \% \ B_{\text{Total}} \), for partly convective M dwarfs and \( B_{\text{ls}} = 14 \% \ B_{\text{Total}} \), for fully convective M dwarfs (right-hand column). A comparison of the extrapolations in both the left- and right-hand columns from Fig. 4 shows the location of coronal holes where the stellar wind is emitted and the angle of the magnetic dipole axis from the rotation pole remain largely unchanged on the majority of the stars in the sample. However, the extrapolations of DT Vir, OT Ser and EQ Peg A show small changes in the structure of the closed large-scale field.

3.2 Activity–rotation relation

The X-ray luminosity has been shown to correlate well with either rotational velocity or Rossby number \( \text{Ro} \) (the ratio of the stellar...
Figure 4. Column (1) shows the 3D coronal extrapolation for the reconstructed surface radial maps for our sample of M dwarfs. Column (2) is the extrapolation for case (2) with the combination of the small-scale field scaled with respect to the large-scale field e.g. $B_{ls} = 6 \text{ per cent } B_{\text{Total}}$, for the partly convective M dwarfs and $B_{ls} = 14 \text{ per cent } B_{\text{Total}}$, for the fully convective M dwarfs.
rotation period, \( P \), to the convective turnover time, \( \tau_c \); e.g. Pizzolato et al. 2003a,b; Jeffries et al. 2011); in general, \( L_X/L_{bol} \) increases and then saturates \( (L_X/L_{bol} \approx 10^{-3}; \text{Delfosse et al. 1998}) \) with increasing rotation rate. This behaviour is attributed to coronal saturation (Vilhu & Walter 1987; Stauffer et al. 1994) and occurs at \( \text{Ro} \approx 0.1 \). For a sample of M dwarfs, Lang et al. (2012) reproduce the saturation of the X-ray emission measure for the large-scale field detected through ZDI. These results are shown in Figs 5 and 6 as black symbols.

With the addition of small-scale field, the correlation between the X-ray emission measure and Rossby number changes depending on the amount of small-scale flux added. For case (1), shown
in Fig. 5, the rise and saturation of the X-ray emission measure is not as prominent with the addition of 500 G of small-scale flux (red symbols) and is no longer evident for 1000 G of small-scale flux (blue symbols). This means that adding the same surface distribution of small-scale field to each star destroys the relationship between magnetic flux and Rossby number. If we now consider case (2) where $B_{ls} = 6 \text{ per cent } B_{\text{Total}}$, for the partly convective M dwarfs, and $B_{ls} = 14 \text{ per cent } B_{\text{Total}}$, for the fully convective M dwarfs shown in Fig. 6, the rise and saturation of the X-ray emission with Rossby number is once again apparent. The magnitude of the X-ray emission has increased by approximately five orders of magnitude due to the increase in flux (Table 2).
For comparison with our previous work (Lang et al. 2012) conducted on the field visible only to ZDI, we keep the model parameters e.g. the temperature ($T = 2 \times 10^4$ K), source surface ($R_{\text{eq}} = 2.5 R_\odot$) and $\kappa = 10^{-6}$, constant. Keeping $\kappa$ constant results in an increase in pressure and coronal density due to the increase in the surface flux. The coronal densities (shown in Table 2) now lie at the higher end of the accepted range: $10^9-10^{12}$ cm$^{-3}$ (Ness et al. 2002, 2004), as opposed to their previous values which were at the lower end. The value of $\kappa$ could be altered in such a way to reduce the coronal densities back to the values calculated for the ZDI maps and in turn reduce the magnitude of the X-ray emission measure.

Comparison of the results of Figs 5 and 6 indicates that the addition of the same small-scale field to each star removes the activity–rotation relation; however, scaling the small-scale field to the large-scale, e.g. $B_{\text{l}} = 500$ G, for the partly convective M dwarfs and $B_{\text{l}} = 1000$ G, for the fully convective M dwarfs, recovers the relation. This would suggest that the small-scale field has the same dependence on rotation period as the large-scale field. Our results are in agreement with that of Garraffo et al. (2013) who find that the small-scale field structure (of similar spatial resolution) plays a crucial role when modeling the closed loop structure.

In our previous work (Lang et al. 2012), the rotational modulation of the X-ray emission measure for the stellar sample did not demonstrate any trend with Rossby number and could not be used as an indicator of field topology due to too many contributing factors e.g. the angle of stellar inclination and the angle of the magnetic dipole axis from the rotation pole. We find that with the addition of small-scale field, both with the same surface distribution and magnitude, and scaled with respect to the large-scale field, this is still the case.

With the addition of small-scale field, the magnitude of the rotation modulation of the X-ray emission measure changes for each star as a result of changes in surface field strength (see Table 2). For OT Ser, an early M dwarf, the change in the rotational modulation between the large-scale field and the addition of small-scale flux is nearly 30 per cent, whereas for GJ 49, also an early M dwarf, the change in the modulation is 1 per cent. Since we do not find any great change in the large-scale field structure with the addition of small-scale field, the trend is nearly linear with Rossby number.

Table 2. Results for the coronal properties for the sample of M dwarfs. The predicted values for the logarithmic emission measure (both magnitude, log EM, and rotational modulation, Rot Mod) and logarithmic coronal density, log $\pi_c$, for the observed large-scale field, are from Lang et al. (2012). The logarithmic emission measure (both magnitude, log EM, and rotational modulation, Rot Mod) and logarithmic coronal density, log $\pi_c$, for the simulated large-scale+small-scale field at $B_{\text{max}} = 500$ and $1000$ G as well as for $B_{\text{l}} = 6$ per cent $B_{\text{total}}$ for partly convective stars and $B_{\text{l}} = 14$ per cent $B_{\text{total}}$ for fully convective stars, are from this work.

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small-scale field, the change in the magnitude of the rotational modulation could be a result of the small-scale field producing low-lying small closed field regions which carpet the stellar surface including the areas where the large-scale field is open.

### 3.3 Open flux and spin-down

Coronal structure is important as it determines the X-ray emission from regions of closed magnetic field but also areas where the magnetic field is open and the stellar wind forms. For stars with weaker large-scale magnetic fields, the range of field strengths present on the star has been altered by the addition of small-scale field. This has little effect on the geometry of the large-scale field (Fig. 4). The dipole axis and the location and extent of the open field regions are largely unchanged. This is to be expected as the small-scale field is distributed axisymmetrically over the surface so it has no preferred direction. This suggests that the latitudes from which a stellar wind could be launched would not be affected by the presence of small-scale field. Within regions where the large-scale field is open there may still be a carpet of small-scale field, which could contribute to powering the stellar wind (e.g. Nishizuka et al. 2011).

The stellar wind is responsible for angular momentum loss and influences the stellar spin-down time. To investigate the effect the small-scale field has on the overall coronal structure, we examine both its influence on the total magnetic flux at the surface of the star and also the total open flux. We analyse the geometry of the field by predicting and comparing the open flux to observed surface flux values obtained from the overall combination of $l$ and $m$ modes:

$$\frac{\Phi_{\text{Open}}}{\Phi_{\text{Surface}}} = \frac{R_*^2 \int |B_{l}(R_*, \theta, \phi)| d\Omega}{R_*^2 \int |B_{l}(R_*, \theta, \phi)| d\Omega}, \tag{10}$$

where $\Omega$ is the solid angle. We note this gives a lower limit to the true open flux as on some field lines the gas pressure may exceed the magnetic pressure.

Adding in small-scale field increases the surface flux. Fig. 7(a) shows this increase expressed as

$$\Delta \Phi_{\text{Surface}} = \frac{(\Phi_{\text{Surface}})_{\text{large+small}}}{(\Phi_{\text{Surface}})_{\text{large}}} - 1. \tag{11}$$

The fractional increase in surface flux is clearly greatest for those stars whose large-scale surface flux is lowest.

The addition of the small-scale field also results in a slight change (10–40 per cent) in the open flux (Fig. 7(b) but shows no preference between partly convective and fully convective stars. The fraction for the open flux is given by

$$\Delta \Phi_{\text{Open}} = \frac{(\Phi_{\text{Open}})_{\text{large+small}}}{(\Phi_{\text{Open}})_{\text{large}}} - 1. \tag{12}$$

This result is in keeping with the increase in surface flux, which would increase the magnetic pressure (equation 5). We note that the magnitude of the open flux is dependent on the chosen value for the source surface (as $R_{ss} \rightarrow \infty$, $\Phi_{\text{Open}} \rightarrow 0$) but the effect of adding in small-scale field is the same for all values of the source surface. As there is little change in the open flux with the addition of small-scale field, we would not expect the angular momentum or mass loss to be significantly affected. These results agree with the MHD-model used by Garraffo et al. (2013).

For many stars a full surface magnetic map is not available and only a single flux estimate is possible. Assuming that all of the surface flux is contained in one single mode, for example a dipole, can however lead to an overestimate of the amount of open flux. As discussed in Lang et al. (2012), the open flux for any single mode is simply related to the surface flux as

$$\Phi_{\text{Open}} = \frac{(2l + 1) \left( \frac{R_*}{R_{ss}} \right)^{l+1}}{l + (l + 1) \left( \frac{R_*}{R_{ss}} \right)^{2l+1}}. \tag{13}$$

Fig. 8 shows that when small-scale field is added there is an increase in surface flux but the predicted open flux is still at least an order of magnitude smaller than it would be had we only considered the dipole modes. Therefore, the angular momentum loss, $J$, due to the stellar wind, which is determined by the amount of open flux, i.e. a Weber–Davis model (Weber & Davis 1967), given by

$$J \propto \Phi_{\text{Open}}^2 \tag{14}$$

is influenced by the topology of the field and would be overestimated by at least two orders of magnitude. This is also true for the mass-loss rate,

$$\dot{M} \propto \Phi_{\text{Open}}, \tag{15}$$

which could be overestimated by an order of magnitude if the topology is oversimplified. We conclude from this result that when producing a model for the stellar corona, or the stellar wind, a range of $l$ and $m$ modes must be considered to reproduce the correct, more complex, coronal structure.
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4 SUMMARY

We have created a model for small-scale field using synthesized spot distribution maps. We allocate field strengths in a Gaussian distribution from the centre of the spot by either (1) fixing the value of \( B_{\text{max}} \) to be either \( \pm 500 \text{ G} \) or \( \pm 1000 \text{ G} \); or (2) setting the value of \( B_{\text{max}} \) such that the large-scale field contributes only 6 per cent of the total field for partly convective M dwarfs and 14 per cent of the total field for fully convective M dwarfs, as indicated in Reiners & Basri (2009). We have incorporated the radial surface map produced by this model into the reconstructed maps of the observed radial magnetic field at the stellar surface for a sample of early-to-mid M dwarfs and extrapolated their 3D coronal magnetic field using the PFSS method.

We have investigated the effect of the addition of small-scale field on the topology of the large-scale magnetic field at the stellar surface and the structure of the extrapolated 3D corona. By assuming a hydrostatic, isothermal corona, we have determined the following.

1. The geometry of the magnetic field e.g. the angle of the dipole axis, overall large-scale structure of the 3D extrapolated corona and location of coronal holes where the stellar wind is emitted all remain largely unchanged.

2. Addition of the same small-scale field to each star removes the \( L_X - \sigma \) relation; however, scaling the small-scale field to the large-scale (ZDI) field recovers the relation. We conclude from this that the small-scale field has the same dependence on rotation period as the large-scale field.

3. The magnitude of the rotational modulation of the X-ray emission measure changes with the addition of more surface flux; however, no trend with Rossby number \( \sigma \) is found. This change could be due to the carpet of low-lying field.

4. The addition of small-scale field increases the surface flux.

5. And finally, we find that the large-scale open flux does not vary greatly with the addition of small-scale field. This suggests that the mass-loss rate, the angular momentum loss and the spin-down time for a star are not significantly affected by small-scale flux.

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