

Social learning of arbitrary food preferences in bonobos

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Highlights

- Bonobos socially learn and copy the arbitrary food preferences of others.
- Bonobos copied others' arbitrary preferences of novel foods on first attempts.
- Subject age and exposure time have a positive effect on successful social learning.
- Copied food preferences can remain stable despite having better knowledge.

ABSTRACT

A fruitful approach to investigate social learning in animals is based on paradigms involving the manipulation of artefacts. However, tool use and elaborate object manipulations are rare in natural conditions, suggesting that social learning evolved in other contexts where fitness consequences are higher, such as discriminating palatable from noxious foods, recognising predators or understanding social hierarchies. We focussed on one such context by investigating whether bonobos socially learned others' arbitrary food preferences through mere observation. To this end, we trained two demonstrators to prefer or avoid distinctly coloured food items, treated with either a sweet or bitter agent. Demonstrators then displayed their newly acquired preferences in front of naïve subjects. In subsequent choice tests, subjects generally matched their choices to the demonstrators' preferred food colours, despite having already tasted the equally palatable colour alternative. Both age and exposure to demonstrator preference had a significant positive effect on the proportion of matched choices. Moreover, in a context where errors can be costly, social learning was instant insofar as six of seven subjects used socially learned information to influence their very first food choice. We discuss these findings in light of the current debate on the evolution of social learning in animals.

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21 **ABSTRACT**

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23 the manipulation of artefacts. However, tool use and elaborate object manipulations are rare

24 in natural conditions, suggesting that social learning evolved in other contexts where fitness

25 consequences are higher, such as discriminating palatable from noxious foods, recognising

26 predators or understanding social hierarchies. We focussed on one such context by

27 investigating whether bonobos socially learned others' arbitrary food preferences through

28 mere observation. To this end, we trained two demonstrators to prefer or avoid distinctly

29 coloured food items, treated with either a sweet or bitter agent. Demonstrators then displayed
30 their newly acquired preferences in front of naïve subjects. In subsequent choice tests,
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32 having already tasted the equally palatable colour alternative. Both age and exposure to
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34 choices. Moreover, in a context where errors can be costly, social learning was instant insofar
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36 choice. We discuss these findings in light of the current debate on the evolution of social
37 learning in animals.

38

39 Keywords: cognition; foraging; nonhuman primate; novel food; *Pan paniscus*; social learning

40 **1. Introduction**

41 Over the past decades, social learning has become a major topic in the field of comparative
42 cognition (Whiten and van de Waal, 2018). Social learning, or more specifically “learning
43 that is influenced by observation of, or interaction with, another animal (typically a
44 conspecific) or its products” (Heyes, 1994) can be highly adaptive as it allows individuals to
45 avoid costly trial-and-error learning, saving both time and energy and avoiding dangerous
46 mistakes (Hopper et al., 2011). Furthermore, social learning can favour the rapid spread of
47 advantageous behavioural innovations and, as such, acts as a ‘second inheritance system’ in
48 addition to phylogenetically acquired behavioural traits (Whiten, 2005). Social learning is
49 likely to be adaptive in many domains, including foraging, mate choice or predator avoidance
50 (Galef and Giraldeau, 2001; Galef and Laland, 2005) and can even take place between
51 species. Indeed, within a given ecological niche, different species are likely to be faced with
52 the same requirements and constraints, as such, information acquired from heterospecifics

53 can be just as valuable as that acquired from conspecifics (Avarguès-Weber et al., 2013). For
54 example, the existing literature documents cases of interspecific social learning of food
55 source location in insects (Dawson and Chittka, 2012) and fish (Coolen et al., 2003), of
56 predator recognition and avoidance in mammals (Kitchen et al., 2010; Zuberbühler, 2000)
57 and reptiles (Vitousek et al., 2007) and of nesting site preference in birds (Seppänen and
58 Forsman, 2007). The importance of social learning is particularly relevant for young and
59 naïve individuals, who can avoid costly or maladaptive behaviour by observing and learning
60 from more experienced and older individuals that have, essentially, survived to adulthood in a
61 given environment (Galef and Laland, 2005).

62

63 Over the years, substantial efforts have been made to investigate the mechanisms underlying
64 social learning across different groups of animals, using both observational and experimental
65 techniques in the wild (e.g. apes: Hobaiter et al., 2014; monkeys: Kawai, 1965; birds: Aplin
66 et al., 2014) and in captivity (e.g. apes: Clay and Tennie, 2018; Dindo et al., 2011; Whiten et
67 al., 2005; monkeys: Dindo et al., 2008; van de Waal et al., 2013b; lemurs: Stoinski et al.,
68 2011; birds: Auersperg et al., 2014; see Reader and Biro, 2010 for a non-exhaustive survey).

69 A common approach to study social learning processes has been to use paradigms that
70 require manipulation of a container ('puzzle box') to extract an edible reward. A particularly
71 successful variant is the 'artificial fruit' (Whiten et al., 1996), which can be opened through
72 various means (e.g. lifting or sliding a door) to obtain a reward within. Such experiments
73 have brought to light not only evidence of social learning (e.g. van de Waal et al., 2010,
74 2013b) and social diffusion (e.g. Dindo et al., 2008, 2011; Whiten and Mesoudi, 2008) but
75 also of social conformity in animals (e.g. Dindo et al., 2009; Whiten et al., 2005). Overall,
76 these findings have broad implications for theories of the evolution of culture (see Whiten

77 and van de Waal, 2016a for a review) as they begin to unravel the basic building blocks for
78 the human capacity for culture, many of which are shared with non-human primates.

79

80 Another particularly common experimental paradigm in the laboratory is to expose subjects
81 to inaccessible food rewards that can only be accessed using a tool (e.g. Call and Tomasello,
82 1994; Horner and Whiten, 2005). However, while tool use is taxonomically widespread, it is
83 generally rare in most primate and non-primate species (Hunt et al., 2013), raising questions
84 on the extent to which experimental paradigms based on tool use are adequate to investigate
85 social learning capacities in such species. Most primates are capable of rich arrays of
86 manipulations, such as twisting, pulling, or peeling, but these manipulations tend to be
87 structurally simple (but see Byrne et al., 2001) and rarely involve tool use. Moreover,
88 although some chimpanzee communities have well established tool traditions (Visalberghi et
89 al., 2015) others only rarely use tools (Lamon et al., 2017; Lamon and Zuberbühler, 2015;
90 Reynolds, 2005), and tool use is curiously absent in wild bonobos (Koops et al., 2015) and
91 many other primate species. However, although social learning may give naïve observers an
92 advantage in some types of problem solving such as moss-sponging in chimpanzees
93 (Hobaiter et al., 2014) and nut-cracking in tufted capuchins (Coelho et al., 2015) and
94 chimpanzees (Marshall-Pescini and Whiten, 2008), and although this capacity for tool use
95 may translate into fitness consequences in certain contexts, for example, by providing highly
96 nutritional foods when usual food resources are scarce (Yamakoshi, 1998), tool use may not
97 be as significant for survival as general foraging strategies.

98

99 Social learning, in other words, may be better investigated in relation to more universally
100 ecologically relevant challenges, such as learning how to interact with socially powerful
101 group members or neighbouring groups or learning how to identify animal species that can

102 pose a predatory threat. Indeed, a recent study has revealed that chimpanzees learn rapidly
103 from each other how to react to humans, a major predator of chimpanzees (Samuni et al.,
104 2014). Regarding more ecologically relevant generalised foraging strategies, one of the key
105 domains for social learning is to discriminate edible from noxious foods (van de Waal et al.,
106 2014, 2013a). Although neophobia is clearly adaptive when encountering novel foods
107 (Addessi et al., 2005), it exposes individuals to starvation when environmental conditions
108 become unstable. A more adaptive strategy may be to follow a ‘copy-when-uncertain’
109 strategy when relying on individual learning alone is risky (Laland, 2004). Evidence of social
110 learning of food choice has been brought to light in several bird species (e.g. house sparrows:
111 Fryday and Greig-Smith, 1994; red-winged blackbirds: Mason and Reidinger, 1981) but also
112 in primates, where food-related social learning is influenced by a number of factors. These
113 include sex, rank, age and association (Coussi-Korbel and Fragaszy, 1995) and while in some
114 species ingestion of novel foods is facilitated by the mere presence of conspecifics, regardless
115 of what they eat (e.g. tufted capuchin: Addessi and Visalberghi, 2001; chimpanzee: Finestone
116 et al., 2014), in others, individuals appear to learn something about the palatability of foods
117 by observing others (e.g. cotton-top tamarin: Snowdon and Boe, 2003; vervet monkey: van
118 de Waal et al., 2013a). Acquisition of such social information may be permitted by simple
119 social learning processes such as stimulus or local enhancement (Whiten and van de Waal,
120 2018).

121

122 One important factor in primate social learning of foraging behaviour is the attention that
123 young and naïve individuals pay to adult behaviour (Rapaport and Brown, 2008). Immature
124 individuals often wait for more experienced individuals to begin foraging before following
125 suit with the same food (e.g. Tarnaud, 2004; Whitehead, 1986; reviewed by Rapaport and
126 Brown, 2008). In apes, adult chimpanzees show more caution and close observation of

127 conspecific food-handling when presented with novel foods than familiar ones (Gustafsson et
128 al., 2014). Infant apes are very attentive to their mothers during foraging and show high rates
129 of co-feeding (Jaeggi et al., 2010; Rapaport and Brown, 2008; Ueno and Matsuzawa, 2005).
130 Food sharing and co-feeding between mother and offspring seem to provide infants with
131 direct learning opportunities and has been observed in lowland gorillas, orangutans,
132 chimpanzees and bonobos (see Rapaport and Brown, 2008 for review). Interestingly, this
133 effect can be so strong that in orangutans, for example, the diet differences between mothers
134 is larger than between mothers and their offspring (Jaeggi et al., 2010). Despite these
135 considerations, individual learning remains an important mechanism for acquiring food
136 aversion (e.g. pigtail macaques, spider monkeys, Fairbanks, 1975; tufted capuchins,
137 Visalberghi and Addessi, 2000) or complex forms of food processing (e.g. nettle feeding in
138 gorillas, Tennie et al., 2008). Some feeding behaviours are even thought to be part of species-
139 specific behavioural repertoires (e.g. rough-leaf swallowing in chimpanzees and bonobos,
140 Menzel et al., 2013) although social influences likely aid the spread of such behaviours
141 (Huffman and Hirata, 2004). Following an initial phase in which young primates
142 preferentially learn from their mothers, their pool of accessible information broadens as their
143 social learning strategies evolve and they begin to learn from other group members (Whiten
144 and van de Waal, 2018).

145

146 When these strategies lead to learning from other group members, then selectiveness for
147 specific models can become apparent. In a recent review, Whiten and van de Waal (2018)
148 presented four selective learning biases evidenced in primates when they learn from other
149 group members. Namely, bias for 'knowledgeable' or 'expert' models; for older models, for
150 models of a specific sex or for conformity (i.e., copying a behaviour expressed by a majority
151 of one's group). Indeed, a general finding in empirical work on social learning in primates

152 highlights the importance of the seeding demonstrator's identity. Chimpanzees, for example,
153 show a clear bias for copying older, higher-ranking and more knowledgeable individuals
154 (Biro et al., 2003; Kendal et al., 2015). However, low ranking individuals may be just as
155 effective in seeding novel behaviours when there is no 'model competition' (i.e., when there
156 are no older or higher ranking individuals acting as demonstrator) (Watson et al., 2017). Yet,
157 in a recent field study with chimpanzees, a novel behaviour, 'moss-sponging' invented by the
158 alpha male, was shown to spread through the community via two transmission patterns.
159 Initial spreading was within a spatio-temporal, proximity-based cohort but then mainly
160 through the matriline (Lamon et al., 2017), a pattern not previously reported in captive
161 groups. The study thus indicated considerable flexibility of behaviour transmission patterns
162 in chimpanzees. Indeed, in recent years, evidence for the flexible use of social learning
163 strategies (i.e., what, when and whom to copy) has been found in several species spanning
164 across taxa, from fish and birds to rats and primates (see Kendal et al., 2018; and Rendell et
165 al., 2011 for reviews). This flexible use of social learning strategies is reflected in changes
166 linked to ontogeny, experience, state and context (Kendal et al., 2018) and is likely an
167 important factor as individuals enter the third phase of social learning proposed by Whiten
168 and van de Waal (2018), which occurs when individuals migrate to new groups and are
169 confronted with new locations and populations. For example, in an experiment in the wild,
170 migrating male vervet monkeys abandoned their personal food preferences to adopt an
171 opposite preference shown by their new group, which has been interpreted as potent social
172 learning with a conformist bias (van de Waal et al., 2013a; Whiten and van de Waal, 2016b).
173
174 In the midst of these potential strategies for social learning, we were interested in
175 experimentally assessing social learning in bonobos, in a universally ecologically relevant
176 situation, i.e., food choice. In the present study we tested whether bonobos are able to

177 socially learn the arbitrary food preferences of a group member acting as demonstrator
178 through mere observation and whether they would adopt and maintain such preference
179 regardless of their own knowledge that both options were equally palatable. To achieve this
180 we ran a social learning experiment comprising of a series of experimental blocks in which
181 subjects observed two demonstrators consistently choosing food items of one novel colour
182 over another. Subjects were then tested to find out whether they preferred to choose food of
183 the same colour as the demonstrator. We predicted that, if subjects observed demonstrators
184 exhibiting a clear choice bias for one novel food colour over another, they would match this
185 bias above chance level in subsequent choice tests. As subjects had no prior experience with
186 these artificially coloured foods, we predicted social learning to be particularly strong during
187 the first experimental block when subjects were still naïve relative to these foods. We were
188 also interested in whether subjects were prepared to maintain such socially learned food
189 preferences, even after having experienced the respective colour alternatives.

190 **2. Methods**

191 *2.1 Ethical Note*

192 The study was authorised and ethically approved by the management of “La Vallée des
193 Singes”. Although two individuals were regularly isolated for short periods of time (<30 min)
194 during this study, they were specifically selected based on their propensity to choose isolation
195 from the group on occasion thus avoiding stress for both the isolated individuals and the
196 group as a whole. The keeper isolated the individuals using methods regularly used on the
197 group when encouraging individuals to pass from one cage to another. When stress was
198 detected within the group, testing was postponed. The study was in line with
199 recommendations in the ARRIVE guidelines, and Animal Behaviour (1992) as well as the
200 EAZA and the AFdPZ code of ethics.

201 2.2 Study Site and Subjects

202 The experiment took place between February and November 2014 at La Vallée des Singes
 203 primate park, Romagne (France). Study subjects were selected from a large group of captive-
 204 born bonobos ($N = 17$, 8 males and 9 females, age range: 14 months - 45 years, mean = 15.2
 205 years, see table 1), housed in a large indoor enclosure (400m²) with access to two outdoor
 206 wooded islands covering 11,500m² in total.

207

208 **Table 1.** Study subjects housed at La Vallée des Singes and role in the experiment

Individual	Sex	Birth year	Age-class	Role
Diwani (DW)	M	1996	Adult	Demonstrator
Kelele (KEL)*	M	2004	Adult	Demonstrator
Ulindi (UL)	F	1993	Adult	Observer
Lingala (LNG)	F	2003	Sub-adult	Observer
Lucy (LY)	F	2003	Sub-adult	Observer
Nakala (NK)*	F	2007	Juvenile	Observer
Loto (LO)	M	2009	Juvenile	Observer
Moko (MO)	M	2012	Infant	Observer
Khalessi (KLS)	F	2012	Infant	Observer

209 Individuals marked by an asterisk had the same father; age-class as defined by Kano (1984)

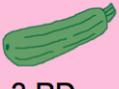
210

211 Two adult males, DW and KEL, were selected as demonstrators based on the ease with which
 212 they could be isolated without apparent signs of stress to any of the group members. Six
 213 experimental blocks were carried out, each consisting of a *Demonstrator Training phase*
 214 (DT) for the demonstrators, followed by a *Preference Demonstration phase* (PD) in front of
 215 the subjects and finally an *Observer Testing phase* (OT) in which subjects underwent
 216 repeated choice tests. Three of the six experimental blocks were in the pink condition (i.e.,
 217 demonstrator preference was for pink courgette) and three in the blue condition (i.e.,

218 demonstrator preference was for blue egg, further details are specified below). Testing was
219 dependent on the personal motivation of each individual to, first, observe the Preference
220 Demonstrations (PD), and, second, participate in the food choice tests of the Observer
221 Testing phase (OT). Therefore, only 7 individuals of the 17 group members (two males and
222 five females, age range: 14 months to 20 years, mean = 7.4 years) participated in the
223 experiment (see table 1). One individual (LNG) participated only in the three experimental
224 blocks of the pink condition, again, due motivational reasons. The remaining six individuals
225 completed all six experimental blocks.

226 *2.3 Experimental Design*

227 We carried out six consecutive experimental blocks, three for the pink condition (P1, P2, P3)
228 and three for the blue condition (B1, B2, B3) (fig. 1). Each experimental block consisted of
229 three distinct phases: (1) Demonstrator Training phase (DT): demonstrators were given the
230 choice between two artificially coloured foods (pink or blue) one of which was rendered
231 unpalatable; (2) Preference Demonstration phase (PD): subjects observed demonstrators
232 choosing their preferred food colours from a distance ranging from approximately 180 cm,
233 across the corridor, to 500 cm on nearby structures or tunnels; (3) Observer Testing phase
234 (OT) : subjects were given the choice between palatable pink or blue food (courgette or egg,
235 see fig 1). For detailed explanations see below. In the pink condition (blocks P1, P2 and P3)
236 demonstrator(s) were presented with pink and blue courgette, and demonstrator preference
237 was for pink courgette. In the blue condition (blocks B1, B2 and B3) the demonstrator was
238 presented with pink and blue egg and demonstrator preference was for blue egg.

	I. Initial preference		II. New preference		III. Maintained preference			
KEL	 P1 3 PD	OT x 5	 B1 6 PD	OT x 5	 B2 4 PD	OT x 5	 B3 4 PD	OT x10
DW	 P1 3 PD				 P2 4 PD	OT x 5	 P3 4 PD	OT x10

239
240

Figure 1. Experimental design - Experimental block order, demonstrator(s) identity, number of Preference Demonstration (PD) days, food used and preferred colour as well as number of Observer Test trials (OT) following each Preference Demonstration phase (PD). Each experimental block began with a Demonstrator Training phase (DT) consisting of 10 food presentations each, not represented on this figure. Testing period for each experimental block in chronological order: P1: Feb, B1: Jul, B2: Aug, B3: Sep, P2: Nov, P3: Nov.

246 *2.3.1 Demonstrator Training Phase (DT)*

247 In the initial Demonstrator Training phase (DT) for the first experimental block (P1), the two
248 demonstrators, DW and KEL, learned that pink courgette was palatable (artificially
249 sweetened), whereas blue courgette was unpalatable (artificially made bitter). In the three
250 following experimental blocks (B1, B2, B3), KEL then learned the reverse colour pattern,
251 albeit with a different food type (i.e., egg). Training for this new preference was achieved by
252 presenting palatable blue egg, and unpalatable pink egg. Finally, in the last two experimental
253 blocks (P2, P3) DW was provided with refresher training for a maintained preference for pink
254 over blue courgette. In total, DW underwent 30 trials of food preference training with the
255 pink courgette, while KEL underwent 10 with the pink courgette and 30 with the blue egg.
256 To this end, at the start of each experimental block, the demonstrators were visually isolated
257 from the rest of the group (Fig. 2a – cage 8, location marked DT) and were offered the choice
258 between the pink and blue food (courgette or egg depending on the experimental block, see
259 fig. 1 for details), one sweet, one bitter. Food presentation lasted 10 seconds after a first
260 choice had been made. The first choice was defined as the first food touched, although in all

261 cases this was also the first food item eaten. Both individuals were given the choice 10 times,
 262 although we found that the colour-taste association was learned after just one experience with
 263 the bitter food. From the next trial onwards, both individuals consistently chose the sweet
 264 colour first and either ignored or only cautiously tasted and discarded the bitter colour
 265 second. Demonstrator Training (DT) was recorded using a PANASONIC HC-V727 full HD
 266 camera equipped with a SENNHEISER MKE 400 external microphone.
 267



268
 269 **Figure 2.** Experimental setup for social learning experiment – a) The Preference Demonstration phase
 270 (PD) is illustrated showing the demonstrator in cage 5 and the observers across the corridor in cage 2.
 271 DT marks the location used in cage 8 for the Demonstrator Training phase; b) Demonstrator choice,
 272 manual food presentation using 20 x 20 cm white plastic trays; c) Observers watching a Preference
 273 Demonstration (PD) from cage 2.

274 *2.3.2 Preference Demonstration Phase (PD)*

275 Following the Demonstrator Training phase (DT), a demonstrator was isolated and given the
276 choice between the pink and blue food (Fig. 2b), while the rest of the group observed his
277 choices from the opposite cage (Fig. 2a - cages 5 and 2 and fig. 2c). Demonstrators were
278 allowed to choose 10 times. Food presentation lasted 10 seconds after a first choice had been
279 made, so that observers could see more clearly which food had been chosen and which had
280 been rejected. Preference Demonstrations (PD) were carried out once a day over several
281 consecutive days (see fig. 1 for details).

282

283 We first ran experimental block P1, in which both DW and KEL were demonstrators and
284 both showed a clear preference for the pink courgette. We chose to start with both
285 demonstrators showing the same preference to increase the salience and strength of the
286 demonstrated preference for the observers. Once established, we proceeded to experimental
287 block B1 in which KEL was sole demonstrator and his colour preference was switched, albeit
288 with a novel food type, so that his preference was for blue egg. We then continued in the blue
289 condition with experimental blocks B2 and B3, again with KEL demonstrating his preference
290 for blue egg. Finally, we carried out experimental blocks P2 and P3, with DW demonstrating
291 his maintained preference for the pink courgette (see fig. 1). The number of demonstration
292 days varied among experimental blocks (i.e. three consecutive demonstration days for each
293 demonstrator in P1, six consecutive days for the sole demonstrator in B1 and four
294 consecutive demonstration days for the sole demonstrator in B2, B3, P2 and P3 resulting in
295 N=170 observable food choices for KEL and N=110 observable food choices for DW in
296 total, see fig. 1).

297 During the Preference Demonstration phase (PD) both the demonstrators and the observers
298 where filmed in order to record both demonstrator colour choice and the number of trials
299 attended to by each observer (demonstrator: PANASONIC HC-V727 full HD camera
300 equipped with a SENNHEISER MKE 400 external microphone; observers: PANASONIC
301 HC-V100 full HD and PANASONIC HC-V727 full HD cameras). Subject attention to
302 demonstrator food choice (i.e., defined as the subject's head and eyes oriented towards the
303 demonstrator whilst the choice was made, regardless of posture) was coded post-hoc by GS
304 from the video footage and from oral commentaries recorded during the demonstrations.
305 Subject attention for a given trial was coded conservatively as either '1' or '0' (i.e., 1 =
306 observing, 0 = not observing). Individuals observing from outside the camera range were
307 recorded with help from a trained animal keeper.

308 *2.3.3 Observer Testing Phase (OT)*

309 Following the Preference Demonstration phase (PD) for each experimental block, observers
310 underwent individual preference testing in which sweetened pink and blue foods (courgette
311 or egg) were presented to them simultaneously. For the Observer Testing phase (OT), both
312 food types were prepared in the same way, but liquid sugarcane was used for all food to rule
313 out any possibility of odour cue-based choices by the observers. Food presentation ended as
314 soon as a choice had been made and was carried out opportunistically on all participating
315 observers (N=7) in all of the indoor cages and the outdoor enclosure.

316

317 Observers were tested five times each in blocks P1, P2, B1 and B2, and 10 times each in
318 blocks P3 and B3. Testing was opportunistic but no two consecutive tests were carried out on
319 a given individual unless the individual had resumed another activity before being retested. In
320 order to avoid feeding competition with other group members, the default protocol was to test

321 subjects in the absence of other group members. It was, however, unavoidable that some
322 subjects (5 of 7) witnessed at least one choice test of another subject. In terms of their overall
323 exposure, this was an insignificantly small proportion with far less influence than the
324 Preference Demonstrations (PD) observed (see supplementary material, table S1). Testing
325 was carried out over two or three consecutive days following the Preference Demonstration
326 phase (PD) and was filmed using a PANASONIC HC-V100 full HD camera in order to
327 record the colour chosen. As choices were always unambiguous and clear, we did not carry
328 out any inter-observer reliability tests.

329 *2.4 Food Preparation and Presentation*

330 Two food types, raw courgettes and cooked egg whites (hereafter ‘egg’), were used
331 throughout the experiment. Individuals were familiar with the natural taste of these foods. For
332 all members of the group, courgette is a lesser-valued food; egg is highly valued, but only
333 familiar as hard-boiled and in the shell. For the first two phases of a given experimental block
334 (i.e., Demonstrator Training (DT) and Preference Demonstration (PD)), the two food types
335 were altered in taste and colour to obtain sweet pink courgette and bitter blue courgette for
336 the pink condition, and sweet blue egg and bitter pink egg for the blue condition. We
337 alternated the colour associated with the palatable food to control for any natural colour bias.
338 The courgette was sliced and quartered (size approximately 2 x 2 x 0.5 cm) before being
339 soaked overnight in either pink food colouring and a sweet additive (liquid sugarcane), or
340 blue food colouring and a bitter additive (Bitrex[®] aqueous solution 2.5%, 0.2ml per 5cl of
341 water: 100ppm). For the egg, either blue food colouring and a sweet additive or pink food
342 colouring and a bitter additive were added before cooking the mixture in a microwave oven
343 and cutting it into small pieces (approximately 2 x 2 x 0.5 cm). For the Observer Testing
344 phase (OT) the two food types were altered in taste and colour to obtain only sweet pink and

345 blue foods and no bitter foods. Pink and blue food colouring were selected as few to no
346 foods of these colours are included in the group's regular diet. We chose not to carry out a
347 control for a natural colour bias as doing so would have provided the subjects with unwanted
348 experience with the two food colours.

349

350 To determine preferred food choice, items were offered manually. To this end, the
351 experimenter (GS) placed a cube of each colour of a given food type on two identical white
352 plastic trays (20 x 20 cm), which were placed, side by side, against the bars of the cages
353 allowing the individual to reach for the food using either the fingers or lips (Fig. 2b). The
354 position (left or right) of the different coloured food items was balanced and pseudo-
355 randomised, insofar as no given colour was presented on the same side for no more than three
356 consecutive trials.

357 *2.5 Statistical Analyses*

358 Statistical analyses were carried out using R 3.1.2., GUI 1.65 and SPSS version 22. Datasets
359 are available online [<https://doi.org/10.17632/tczyxb9wvh.1>]. Wilcoxon exact sign rank tests
360 were used to test comparisons between: 1) Subject attention to the two demonstrators (i.e.,
361 the percentage of DW and KEL Preference Demonstration (PD) trials observed by each
362 subject); 2) Performance in the first choice test, (i.e. number of matched and non-matched
363 choices made in the first test following each Preference Demonstration (PD)). For the overall
364 performance (i.e., the number of matched and non-matched choices made by each subject
365 overall), we ran a Generalised linear model with a quasi-binomial error structure. We
366 modelled the probability of making matched choice across all trials per individual as a
367 function of age and proportion of observed Preference Demonstration (PD) trials.

368 **3. Results**

369 *3.1 Preference Demonstration Phase (PD)*

370 *3.1.1 Demonstrator performance*

371 KEL and DW's performance during Preference Demonstrations (PD) was close to perfect.
372 They chose the correct colour first in 97% and 99% of trials and ate the correct colour
373 exclusively in 95% and 96% of trials, respectively (i.e. pink courgette in P1, P2 and P3 and
374 blue egg in B1, B2 and B3; KEL N=170 and DW N=110, see Preference Demonstration
375 phase (PD) in methods for details).

376 *3.1.2 Attention to demonstrators*

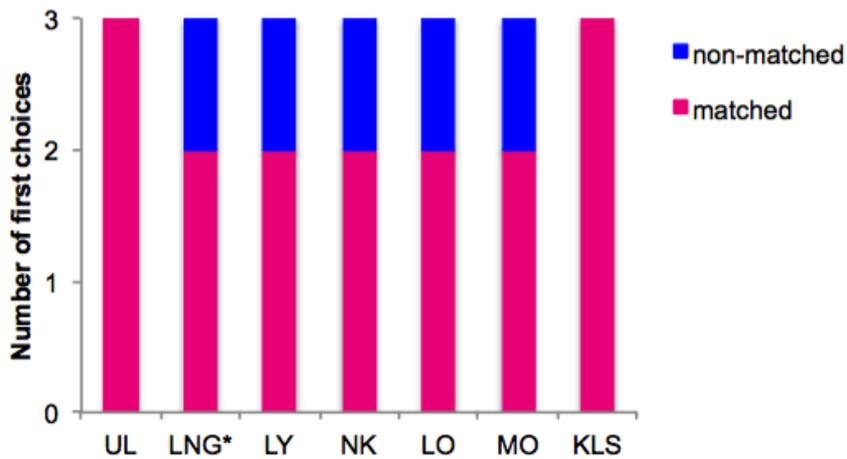
377 While observers paid more attention to Preference Demonstrations (PD) by DW than to those
378 by KEL, the difference was not statistically significant (mean percentage of demonstrations
379 watched by the subjects: DW 35.4%, KEL 29.8%, Wilcoxon exact test, $Z = -1.014$, $N = 7$,
380 exact $P = 0.38$, two-tailed).

381 *3.2 Observer Testing Phase (OT)*

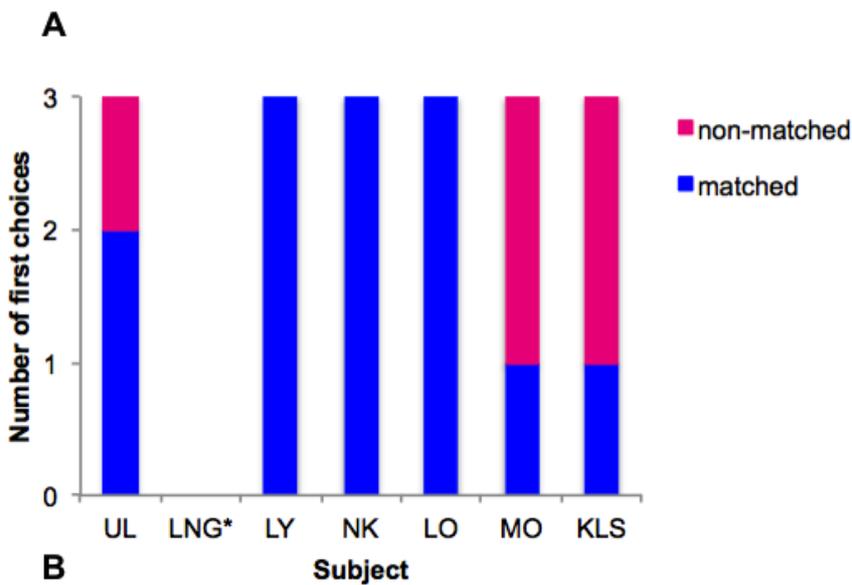
382 *3.2.1 First choice performance*

383 For the first trial of the first experimental block (P1) all observers were naïve having had no
384 personal experience with the artificially altered foods. Nevertheless, six of seven subjects
385 chose the colour chosen by the demonstrator in this first trial. When analysing first choices
386 across all experimental blocks, individuals chose the matched colour significantly more often
387 than the non-matched colour ($Z = -2.64$, $N = 6$, $P = 0.031$, two-tailed, Wilcoxon exact test;
388 Fig. 3; one subject, LNG, could not be included in this analysis as she partook in only 3 of
389 the 6 experimental blocks). Of the seven subjects, six chose mostly the matched colour as

390 their first choice for each experimental block, and only one chose the matched and non-
 391 matched colour equally, suggesting that, as per our predictions, individuals immediately
 392 experienced a significant bias towards the foods chosen by the demonstrators, a clear
 393 demonstration of rapid social learning by observation.
 394



395



396

397 **Figure 3.** Number of matched and non-matched colour choices for each subject in the first choice test
 398 of the Observer Testing phase (OT): A) pink experimental blocks (P1, P2, P3), B) blue experimental
 399 blocks (B1, B2, B3), subjects classed by decreasing age from left to right.

400 3.2.2 Overall performance

401 Taking into account the observers' overall performance in choosing the matched colour,
402 results show that the food preference of the demonstrators continued to have an influence on
403 observer colour choice. Indeed, the model supported the fact that subjects matched their
404 choices to those of the demonstrators significantly above chance levels (see table 2 and figure
405 4 for raw data).

406

407 **Table 2.** Results of the logistic regression modelling the proportion of matched trials (N = 7).

	Estimate	Standard error	Z value	P
Intercept	0.64	0.09	6.85	0.002 ***
Age	7.33	1.60	4.59	0.010 *
Proportion of trials observed	1.65	0.50	3.32	0.029 *

408 Estimates are on a logit scale.

409 This is important because, over the course of the experiment, all observers occasionally tasted
410 the alternative colour choice (i.e., unmatched choice), which was identical in taste and
411 palatability to the matched choice (both treated with liquid sugarcane). Nonetheless, they
412 chose the food colour preferred by the demonstrators more than the alternative.

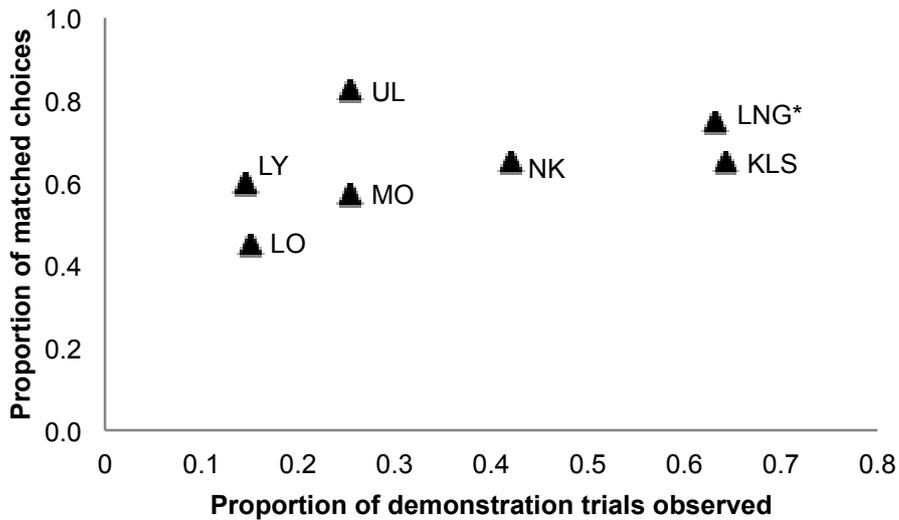
413

Experimental block	Demonstrator preference	Subject						
		UL	LNG*	LY	NK	LO	MO	KLS
P1								
B1								
B2								
B3								
P2								
P3								

414
415 **Figure 4.** Experimental block, demonstrator preference and all subject choices during the Observer
416 Testing phase (OT) for all six experimental blocks (both subject choice trials and experimental blocks
417 are shown in chronological order).

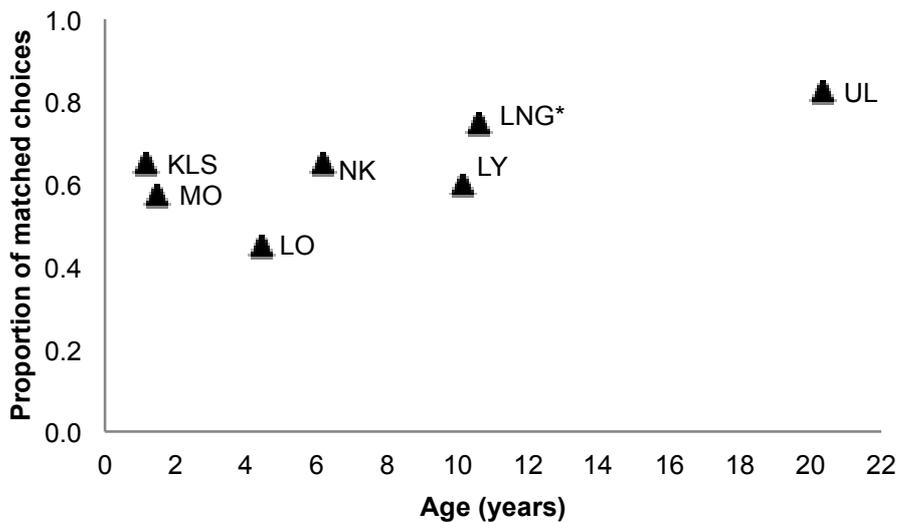
418 Furthermore, both age and proportion of trials observed had a significant positive effect on
419 the proportion of matched choices (Table 2, Figs. 5 and 6).

420



421

422 **Figure 5.** Proportion of matched choices made during Observer Testing phase (OT) and proportion
 423 of Preference Demonstration (PD) trials observed by each subject. LNG, marked by an asterisk,
 424 participated in only P1, P2 & P3.



425

426 **Figure 6.** Proportion of matched choices made during the Observer Testing phase (OT) and subject
 427 age in years. LNG, marked by an asterisk, participated in only P1, P2 & P3.

428

429 When considering individual performance (i.e. percentage of matched choices during the
 430 Observer Testing phase (OT)), it can be noted that there is considerable inter-individual
 431 variability (Table 3), variability which can be explained in part by the age of subjects and

432 their attention to Preference Demonstrations (PD) (as shown in the model). Nonetheless, six
 433 of seven subjects chose the matched food colour more often than the unmatched food colour.
 434

435 **Table 3.** Individual performance over all six experimental blocks

Subject	<i>N</i>	Proportion of demonstration trials observed	Food colour choice matched : unmatched	Performance (% matched)
UL	40	0.25	33:7	82.5
LNG	20	0.63	15:5	75.0
LY	40	0.14	24:16	60.0
NK	40	0.42	26:14	65.0
LO	40	0.15	18:22	45.0
MO	40	0.25	23:17	57.5
KLS	40	0.64	26:14	65.0

436 Proportion of demonstration trials observed, number of matched and unmatched choices and
 437 percentage of matched choices made by subjects. One individual (LNG) participated in the Observer
 438 Testing phase (OT) for only three of the six experimental blocks: P1, P2 & P3.

439 **4. Discussion**

440 In this study we sought to investigate whether bonobos are capable of acquiring and
 441 retaining information relating to arbitrary food preferences of fellow group members
 442 through mere observation. In other words, can bonobos socially learn the different food
 443 preferences of other group members and do they abide to these even if doing so goes against
 444 their own experience and knowledge (i.e., despite knowing that both colour alternatives are
 445 equally palatable)? In our experiment, both demonstrators were exposed to trial-and-error
 446 learning to install an arbitrary preference for visually novel food items, which led
 447 immediately to a clear bias for the palatable food. In a series of six experimental blocks,
 448 subjects were then provided with the opportunity to observe demonstrator preferences before

449 being presented with the choice of two colour alternatives of an otherwise identical food
450 item. The results, as demonstrated by the number of matched choices made by the subjects
451 in the first choice of each experimental block, showed that the subjects had developed an
452 immediate preference for the food item chosen by the demonstrator, demonstrating rapid and
453 reliable social learning. Furthermore, and importantly, this effect occurred despite subjects
454 being exposed to a complex demonstration pattern during which one demonstrator (KEL)
455 demonstrated opposing colour preferences for different foods (see fig. 1). In this paradigm
456 which confronted the subjects with the question of “what to eat?” it is likely that the
457 mechanism at work is simple stimulus enhancement as is often the case with this and other
458 everyday behavioural questions such as “where to sleep?” or “who and what to beware of?”
459 (Whiten and van de Waal, 2018).

460

461 Our second finding relates to the fact that subjects’ performance continued to be biased
462 towards the demonstrated preference, as indicated in the subjects’ overall performance, even
463 after individuals had opportunities to taste the alternatively coloured foods (i.e., when both
464 coloured foods were known to be equally palatable, see fig. 4 for frequencies of alternative
465 colour choice throughout the experiment). We noted considerable inter-individual
466 differences in performance during the crucial Observer Testing phase (OT), which was at
467 least partially explained by subject age and exposure to Preference Demonstrations (PD)
468 (see fig. 5 and 6); indeed, younger individuals and those that observed only a few
469 demonstrations were less likely to match their choices to those of the demonstrators in the
470 Observer Testing phase (OT) than older individuals or those that observed many
471 demonstrations. It seems quite intuitive that performance should improve with increased
472 exposure to demonstrator preference, however, the result observed in relation to subject age
473 is in contradiction with the general finding that suggests that juvenile primates are more

474 prone to use social information than are adults (e.g. Coelho et al., 2015; Matsuzawa, 1994).

475 In the present study we found that older subjects were those most likely to match their

476 choices to those of the demonstrators.

477

478 When considering the possible explanations for subjects generally adhering to demonstrator

479 preferences we must consider the recent findings which have revealed that rather than being

480 set rules, social learning strategies are used flexibly at the individual, group and population

481 level (see Kendal et al., 2018 for a non-exhaustive review of theoretical and empirical

482 support for a broad range of social learning strategies), in fact a recent study in the wild has

483 demonstrated that this flexibility can even be at the species level (Bono et al., 2018). In their

484 review, Kendal et al. (2018) present a variety of strategies as to when, whom and what to

485 copy. In our study, following their initial choice, not only were subjects rapidly exposed to

486 the alternative colour choice, but in choosing the alternative colour they were immediately

487 rewarded, just as they were when copying the demonstrator. And yet in our study, subjects

488 generally adhered to the preference shown by the demonstrator. This propensity to adhere to

489 demonstrator preference might be in line with a ‘when’ learning strategy more expected of

490 naïve subjects: ‘copy-when-uncertain’. This would suggest that subjects perceived

491 uncertainty during testing which increased their willingness to rely on social information

492 (Galef et al., 2008; Kendal et al., 2015) rather than their own experience. In some studies

493 with apes and human children subjects have been found to follow the demonstrator’s strategy

494 even if this meant going against their own personal preference (e.g. human children, Gergely

495 et al., 2002; chimpanzees, Hopper et al., 2011) while in other studies this was not the case

496 (Vale et al., 2017). Vale and colleagues (2017), for instance, demonstrated that chimpanzees

497 preferred to rely on their personal experience with unpalatable foods rather than to conform

498 to group norms. Observation of group members eating the previously ‘unpalatable’ food did,

499 however, promote the re-exploration of that food through social learning. This pattern of
500 relying more on one's own experience than on social information from conspecifics has also
501 been observed in other animal species. For example, Fryday and Greig-Smith (1994),
502 demonstrated that the amount of food consumed by house sparrows was influenced not by
503 demonstrator consumption, but by their own previous experience with the food (i.e., palatable
504 untreated food or unpalatable quinine-treated food).

505

506 Regarding a possible “who” strategy, there is much empirical work to support model-based
507 biases, for instance the propensity to learn from older and higher ranking group members
508 (e.g. Biro et al., 2003; Kendal et al., 2015). In our study, the two demonstrators were not the
509 highest ranking male in the group, nor were they the oldest, and neither one was directly
510 related to any of the subjects, nevertheless social learning took place, as shown, for example,
511 by the results obtained for UL, a high-ranking adult female, who was most strongly
512 influenced by these males (i.e., UL made the highest number of matched choices of all
513 subjects, see table 3 and fig. 4). This result may be indicative of a ‘who’ bias for
514 ‘knowledgeable’ or ‘expert’ models (Whiten and van de Waal, 2018) or perhaps, similarly to
515 chimpanzees, in the absence of ‘demonstrator-competition’ (i.e., the presence of the usually
516 more favoured, older and higher-ranking demonstrators), low-ranking individuals are able to
517 successfully seed a behaviour (Watson et al., 2017). This finding is thus at odds with one of
518 de Waal’s (2001) bonding- and identification-based observational learning model predictions,
519 which is that, for social learning to take place, demonstrators ought to be high ranking
520 individuals, a pattern that has been found in both captive (Horner et al., 2010) and wild
521 chimpanzees (Hobaiter et al., 2014) although kin-based learning may be more important in
522 establishing long-term behavioural traditions (Lamon et al., 2017).

523 Kendal et al. further present a set of frequency-dependant biases. Indeed, potential
524 explanation for subjects adhering to demonstrator preference, despite possessing the
525 knowledge that both foods were equally palatable, might come from some sort of desire to
526 conform (as predicted by de Waal's (2001) BIOL model, although the author predicted a
527 desire to conform specifically to higher ranking and older individuals), perhaps for the sake
528 of social cohesion (Hopper et al., 2011). In humans, this effect is particularly strong if a novel
529 behaviour is shown by several or a majority of group members. Conformity predicts that
530 individuals will change their own behaviour and adopt the majority behaviour in order to
531 comply with what they perceive as 'social norms' (van Leeuwen and Haun, 2014). Whether
532 or not such social influence really requires a majority (e.g. Asch, 1956) or comes into play
533 even when the behaviour has initially been demonstrated by a minority, is often unclear
534 (Hopper et al., 2011; but see Cialdini and Trost, 1984 for a review). In our study we did not
535 test specifically for conformity, since subjects did not have to adhere to the behaviour of a
536 majority, instead we demonstrated that several group members adopted the same preference
537 (non-exclusively) as that expressed by the two demonstrators, and this was despite having
538 knowledge that both foods were equally palatable.

539

540 Another explanation is that subjects were following a sensible survival strategy: if a
541 demonstrator systematically refuses to eat a certain food, then it may be reasonable to assume
542 that he does so for a good reason. In the present case, following the demonstrator's choice
543 and following a 'better-safe-than-sorry' strategy was cost free. The underlying drivers of such
544 behaviour open questions for future research.

545 **5. Conclusion**

546 We conclude that, even in the absence of olfactory and taste cues, bonobos are able to acquire
547 and memorise others' food preferences and are prepared to adhere to them, even when the
548 demonstrator is not a high ranking individual. Bonobos, similar to humans, are susceptible to
549 acquiring information from watching the behaviour of others even if demonstrators are socially
550 unimportant and even adhere to these learned behaviours despite personal knowledge that there
551 is no additional reward in doing so. Furthermore, while this study does not allow us to draw
552 conclusions regarding the exact social learning mechanism(s) at work, the results, even if due
553 to simple stimulus enhancement, as has been suggested for social learning of many of the day-
554 to-day behaviours (Whiten and van de Waal, 2018), demonstrate that subjects matched their
555 choices to those of the demonstrators regardless of the colour, food type and demonstrator
556 identity. We believe this supports not only the fact that learning from others in the context of
557 food acquisition is of paramount importance but also provides further support to the ongoing
558 discussion around the flexible use of social learning strategies.

559 Finally, it is important to point out that our findings were made in the context of an
560 ecologically important situation, i.e. learning about novel foods, which highlights the fact that
561 social learning theory is likely to benefit from paradigms that focus on more universal
562 ecologically relevant problems.

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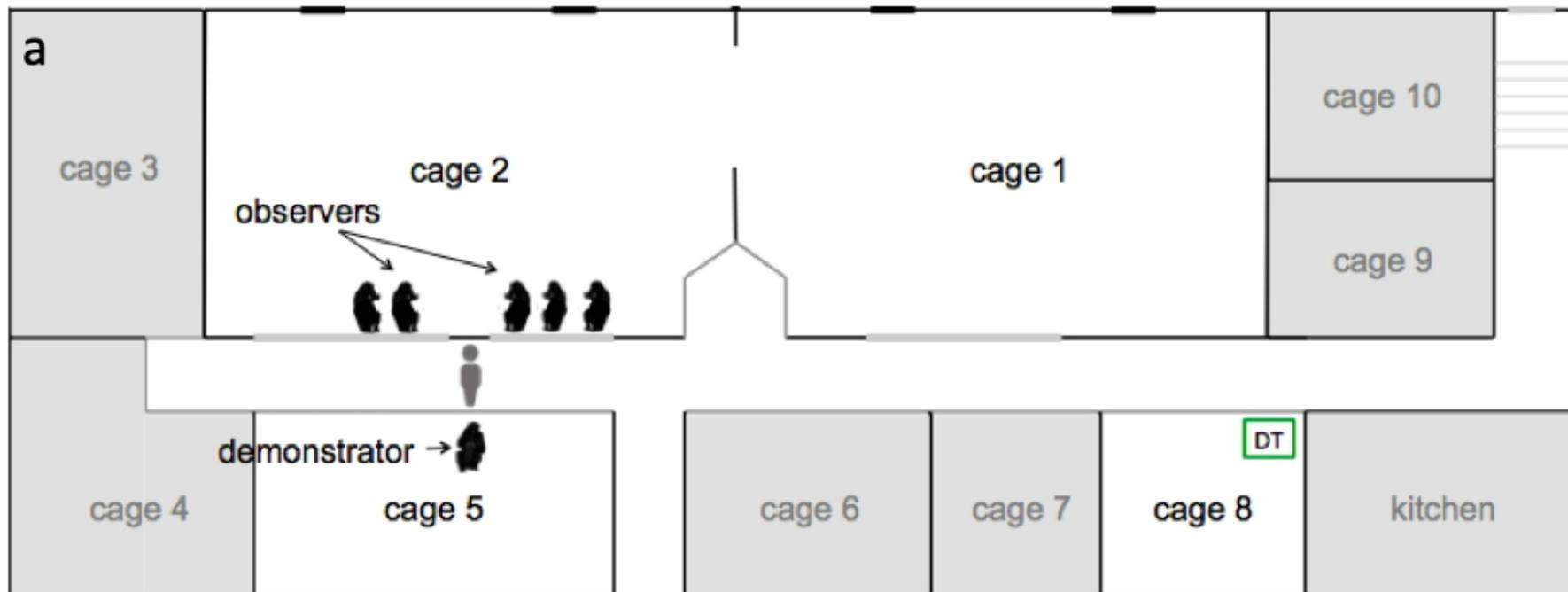
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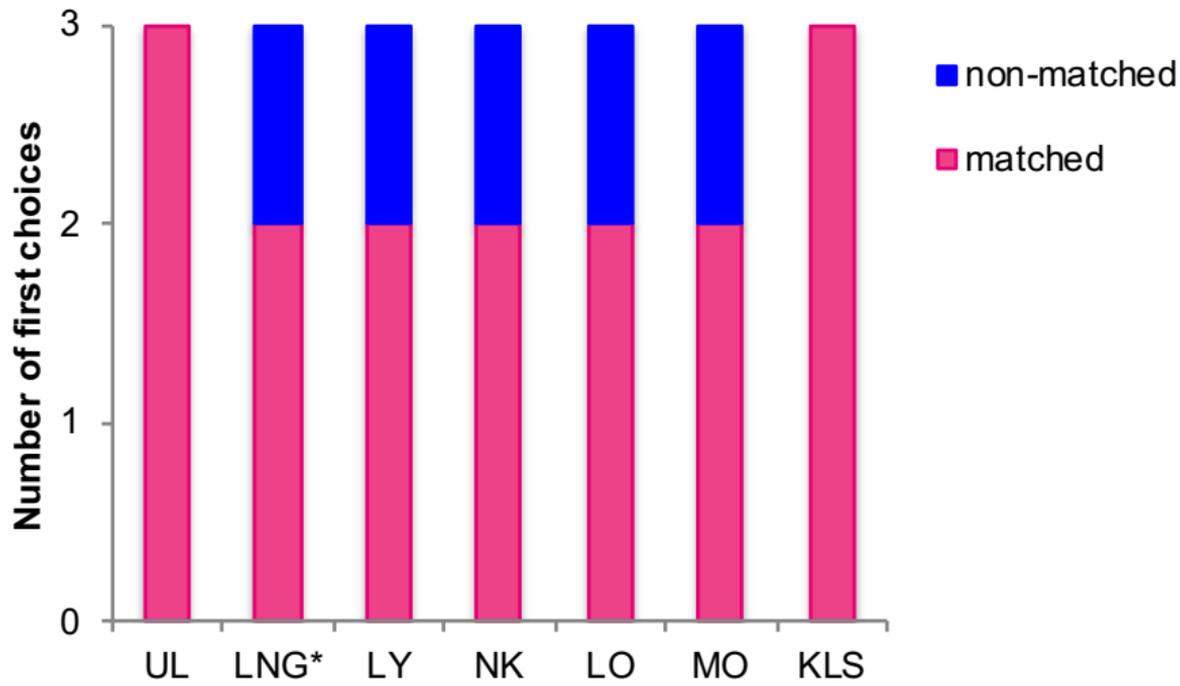
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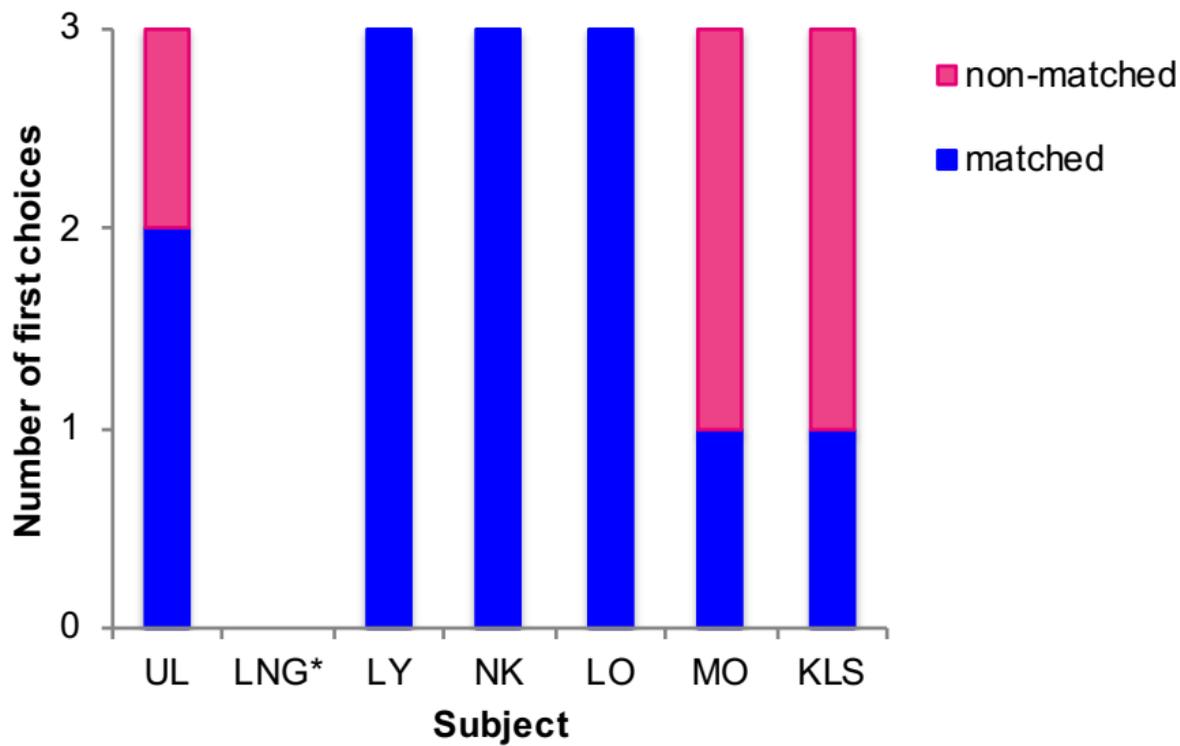
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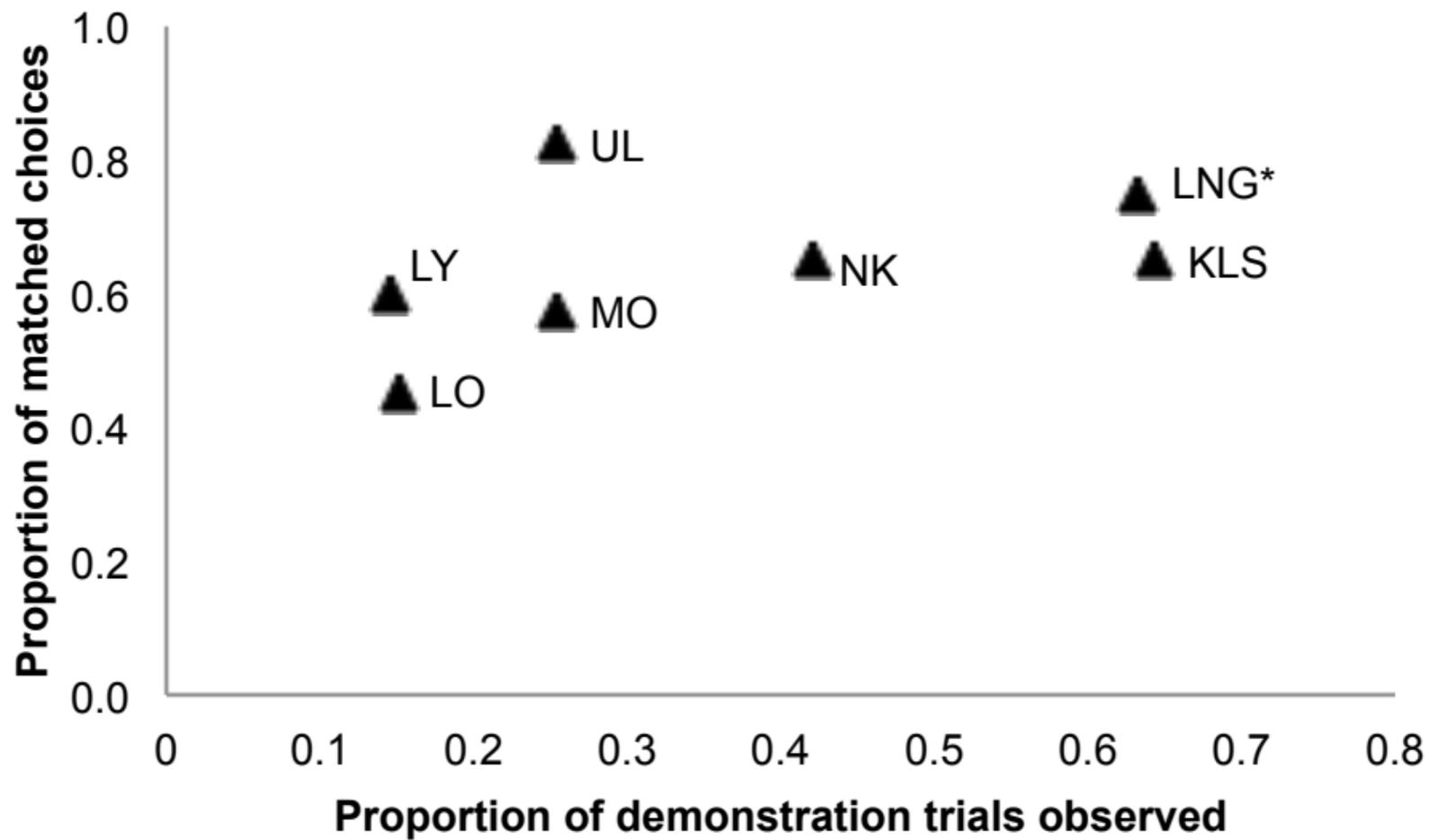
810

	I. Initial preference		II. New preference		III. Maintained preference			
KEL	P1  3 PD	OT x 5	B1  6 PD	OT x 5	B2  4 PD	OT x 5	B3  4 PD	OT x10
DW	P1  3 PD					P2  4 PD	OT x 5	P3  4 PD









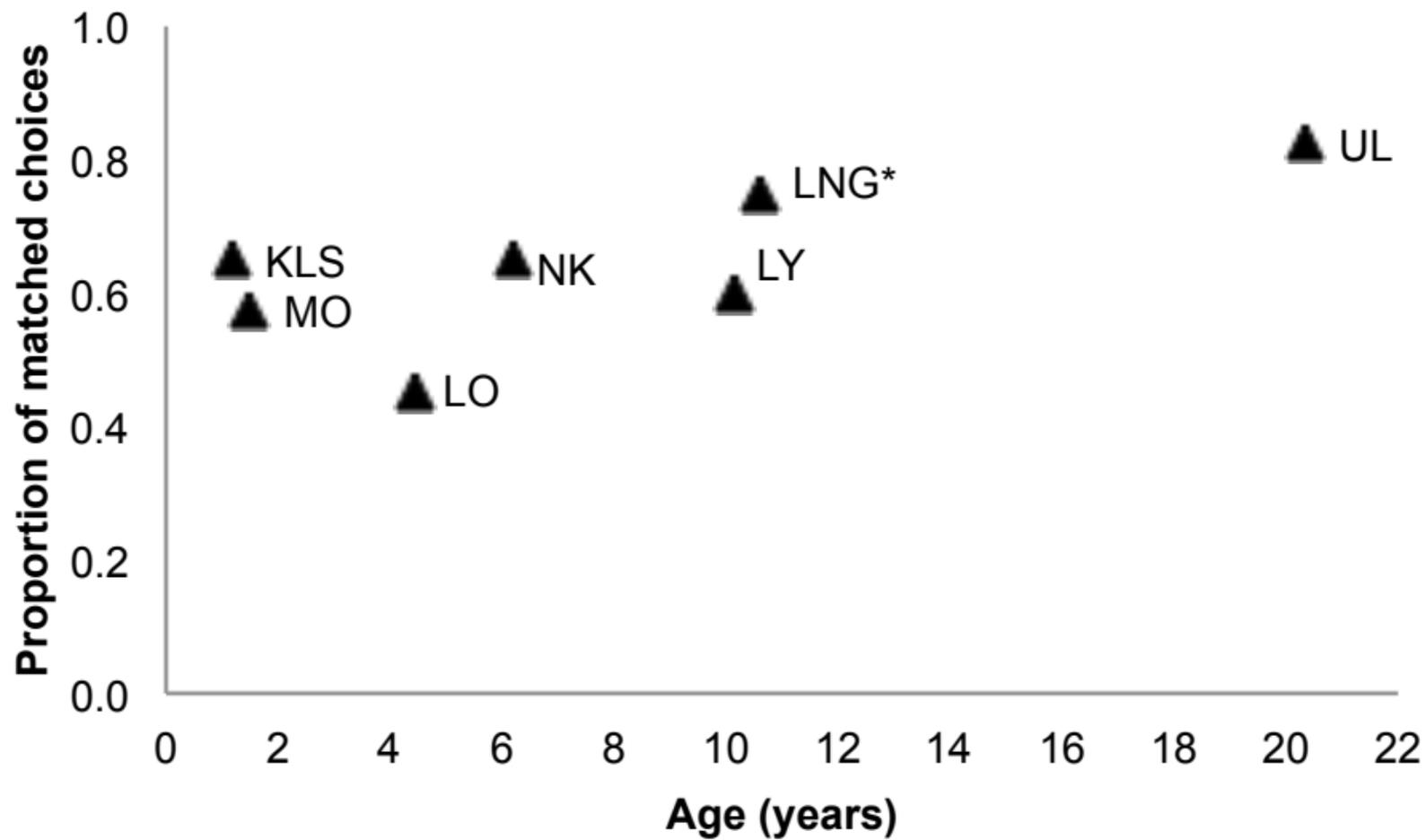


Table 1. Study subjects housed at La Vallée des Singes and role in the experiment

Individual	Sex	Birth year	Age-class	Role
Diwani (DW)	M	1996	Adult	Demonstrator
Kelele (KEL)*	M	2004	Adult	Demonstrator
Ulindi (UL)	F	1993	Adult	Observer
Lingala (LNG)	F	2003	Sub-adult	Observer
Lucy (LY)	F	2003	Sub-adult	Observer
Nakala (NK)*	F	2007	Juvenile	Observer
Loto (LO)	M	2009	Juvenile	Observer
Moko (MO)	M	2012	Infant	Observer
Khalessi (KLS)	F	2012	Infant	Observer

Individuals marked by an asterisk had the same father; age-class as defined by Kano (1984)

Table 2. Results of the logistic regression modelling the proportion of matched trials (N = 7).

	Estimate	Standard error	Z value	P
Intercept	0.64	0.09	6.85	0.002 ***
Age	7.33	1.60	4.59	0.010 *
Proportion of trials observed	1.65	0.50	3.32	0.029 *

Estimates are on a logit scale.

Table 3. Individual performance over all six experimental blocks

Subject	<i>N</i>	Proportion of demonstration trials observed	Food colour choice matched : unmatched	Performance (% matched)
UL	40	0.25	33:7	82.5
LNG	20	0.63	15:5	75.0
LY	40	0.14	24:16	60.0
NK	40	0.42	26:14	65.0
LO	40	0.15	18:22	45.0
MO	40	0.25	23:17	57.5
KLS	40	0.64	26:14	65.0

Proportion of demonstration trials observed, number of matched and unmatched choices and percentage of matched choices made by subjects. One individual (LNG) participated in the Observer Testing phase (OT) for only three of the six experimental blocks: P1, P2 & P3.