

1 **Using self-organizing maps to classify humpback whale song units and quantify their**
2 **similarity**

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24 **ABSTRACT**

25 Classification of vocal signals can be undertaken using a wide variety of qualitative and
26 quantitative techniques. Using east Australian humpback whale song from 2002-2014, a subset
27 of vocal signals were acoustically measured and then classified using a self-organizing map
28 (SOM). The SOM created 1) an acoustic dictionary of units representing the song's repertoire,
29 and 2) Cartesian distance measurements among all unit types (SOM nodes). Utilizing the SOM
30 dictionary as a guide, additional song recordings from east Australia were rapidly (manually)
31 transcribed. To assess the similarity in song sequences, the Cartesian distance output from the
32 SOM was applied in Levenshtein distance similarity analyses as a weighting factor to better
33 incorporate unit similarity in the calculation (previously a qualitative process). SOMs provide a
34 more robust and repeatable means of categorizing acoustic signals along with a clear quantitative
35 measurement of sound type similarity based on acoustic features. This method can be utilized
36 for a wide variety of acoustic databases especially those containing very large datasets, and be
37 applied across the vocalization research community to help address concerns surrounding
38 inconsistency in manual classification.

39

40 I. INTRODUCTION

41 Acoustic signals are commonly used for communication in a variety of species and
42 signals typically convey different kinds of information. Information can range from simple
43 species identification (Gerhardt, 2001) to complicated ideas such as foraging (Slocombe and
44 Zuberbühler, 2006) or social hierarchy (Catchpole and Slater, 2008). Vocal studies are therefore
45 imperative to understanding a broad range of concepts such as species distribution, signal
46 information content, or vocal learning. One major hurdle for any vocalization study is a precise
47 means to analyze data (Kershenbaum *et al.*, 2014). Acoustic features such as duration or
48 frequency can be quantified (Tchernichovski *et al.*, 2000; Cerchio *et al.*, 2001), yet these features
49 do not always provide complete signal representation (Janik, 1999). As a result signals are often
50 classified into categories qualitatively by a human observer (Janik, 1999; Kershenbaum *et al.*,
51 2014).

52 Manual classifications can be corroborated by several means. Naïve matching tests
53 compare agreement between independent observers (e.g., Garland *et al.*, 2011). Quantitative
54 testing can also assess manual classification, including multivariate statistics such as
55 discriminant function analysis (DFA) (e.g., Dunlop *et al.*, 2007), Classification And Regression
56 Trees (CART) (e.g., Melendez *et al.*, 2006, Rekdahl *et al.*, 2013) or Random Forest analysis
57 (e.g., Risch *et al.*, 2013, Garland *et al.*, 2015). Despite quantitative support, classifying signals
58 remains largely qualitative. Automated methods provide more objectivity, but cannot always be
59 implemented if signals are too varied or complex (Janik, 1999). Subjectivity is a key weakness
60 in vocalization studies: it impedes standardized classification across studies of the same vocal
61 display, and there is no reliable way to determine if classifications are biologically relevant to the

62 study species. Different methods are therefore required that can move classification towards a
63 more repeatable and objective approach.

64 One such technique is an artificial neural network called a Self-Organizing Map (SOM)
65 (Kohonen, 1990). What makes the SOM such a beneficial tool is that it uses an “unsupervised”
66 learning algorithm: there is no parameter selection of the data’s variables or user feedback
67 involved in the target classification outputs (Suzuki *et al.*, 2006; Green *et al.*, 2007; Kohonen,
68 2014). Unsupervised learning removes a degree of the subjectivity that can come from
69 predetermining how to group information, which occurs in “supervised” learning (Kohonen,
70 1990; Green *et al.*, 2007). It also allows for the possibility of recognizing patterns that may not
71 be apparent to a human observer (Green *et al.*, 2007). This is advantageous given the
72 aforementioned difficulty with determining a feature’s biological relevance.

73 SOMs organize information into a 2-dimensional “output space” (Bauer and Pawelzik,
74 1992), made up of ‘nodes’ which serve as the categories into which data will be grouped.
75 Before this can happen, the map must learn to classify the dataset in question. Acoustic signals
76 within the dataset are each represented by an input vector of values (i.e. each vector is the list of
77 measured variables). Training occurs by repeatedly presenting the map with each of the input
78 vectors. Each node contains a weight vector of the same length as the input vectors, and the
79 nodes learn to respond to the data during training (Kohonen, 1990). A principal component
80 analysis on the input vectors provides initial values for the weight vectors (Hagan *et al.*, 1996;
81 Kohonen, 2014). SOMs can then place a signal into whichever node has the weight vector that
82 best matches its input vector (Kohonen, 1990; Walker *et al.*, 1996). The spatial arrangement of
83 the nodes is dictated by two parameters: neighborhood size and learning rate. Learning rate
84 controls the extent to which a node is altered, while neighborhood size determines how many

85 surrounding nodes are affected by those alterations (Hagan *et al.*, 1996; Callan *et al.*, 1999). The
86 result is that more similar nodes are arranged to have closer proximity to one another within the
87 map. An added advantage of this spatial arrangement is that the distance between nodes can be
88 measured in either Euclidean or Cartesian space. These measures serve as a means of
89 quantifying similarity between sound types, which can then be utilized in subsequent analyses
90 (Garland *et al.*, 2017). SOMs have been used as a method for analyzing vocal signals in species
91 such as domestic pigs (*Sus scrofa*) (Schön *et al.*, 2001), white-crowned sparrows (*Zonotrichia*
92 *leucophrys pugetensis*) (Ranjard and Ross, 2008), and humans (Callan *et al.*, 1999).

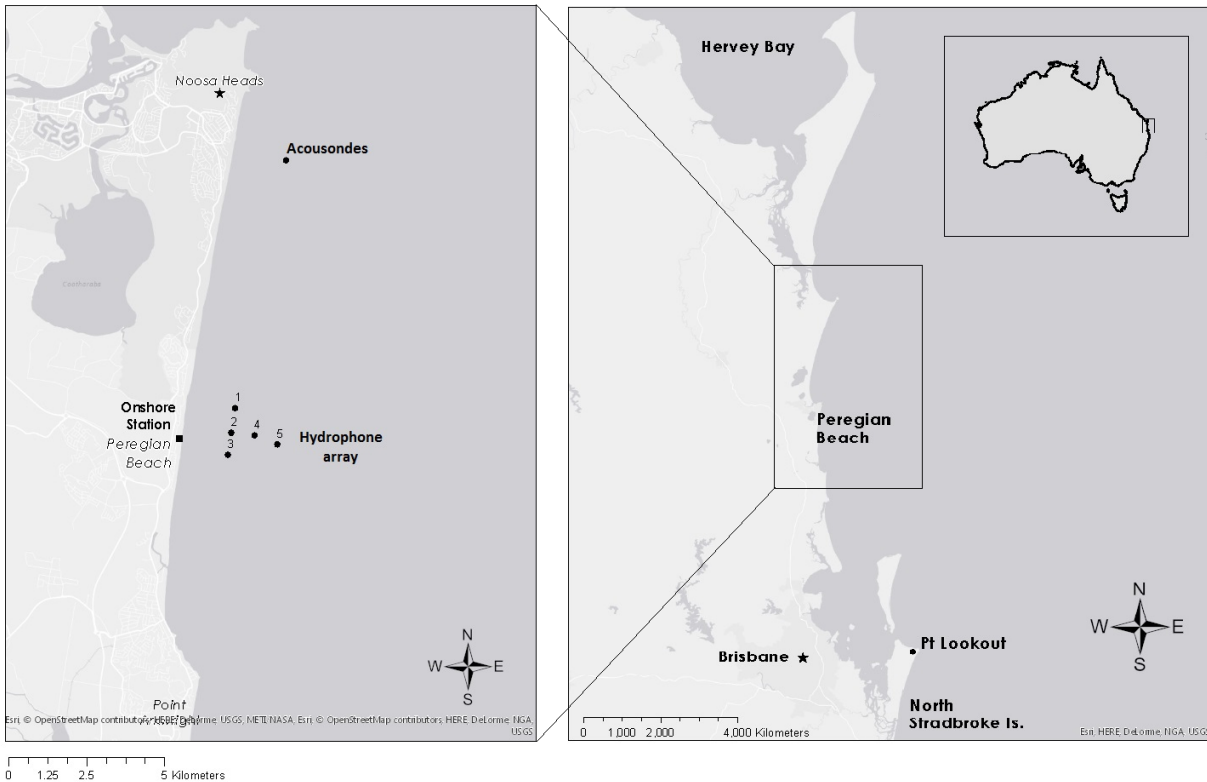
93 SOMs appear particularly useful in the classification of humpback whale song units
94 (Walker *et al.*, 1996; Mercado and Kuh, 1998; Suzuki *et al.*, 2006; Green *et al.*, 2007; Kaufman
95 *et al.*, 2012; Murray *et al.*, 2016). Humpback whale song has a hierarchical structure consisting
96 of sound units repeating in a set pattern to make up a phrase. Phrases then repeat a number of
97 times to form a theme. Themes are repeated sequentially to make up a song cycle (Payne and
98 McVay, 1971; Payne and Payne, 1985; Cholewiak *et al.*, 2013). Although all males in a
99 population typically sing the same song pattern at any given time, the song tends to changes
100 progressively (Payne *et al.*, 1983; Payne and Payne, 1985). Recent work by (Murray *et al.*,
101 2016) expanded on the use of acoustic features for song unit classification by measuring the
102 frequency contours of tonal sounds, and including them as variables in the SOM classification.
103 Classification results were then used to transcribe phrases into numeric strings to represent the
104 unit sequences of those phrases. The Levenshtein distance, a similarity analysis that is highly
105 suited to comparing vocal sequences (Kershenbaum *et al.*, 2014), was then used between
106 transcribed sequences along with cluster analyses to quantitatively identify themes.

107 The degree of complexity and rapid evolutionary change found in humpback whale song
108 make it an ideal model to test the robustness and repeatability of this methodology in highly
109 complex vocal displays. While similar prototypes have been generated before (Walker *et al.*,
110 1996; Mercado and Kuh, 1998), the current study expands on this by creating an acoustic
111 dictionary, a task that has yet to be undertaken in vocalization research (Placer *et al.*, 2006). The
112 size of many acoustic datasets often makes it impractical to measure every signal required to
113 generate large sample sizes of vocal sequences. A dictionary can serve as a guide for the rapid
114 transcription of new, unmeasured recordings into numeric sequences, bolstering sample size.
115 Additionally, by applying SOM distance measurements that provide a quantitative measure of
116 unit similarity in higher-level (sequence) analyses, the utility and repeatability of transcription
117 using this dictionary is apparent. The relative efficiency of SOM classification is also
118 investigated in comparison to the manual classification method when based on the same input
119 data. Use of the SOM method described here provides a more repeatable and robust means of
120 classifying acoustic signals, along with the application of quantified signal similarity in higher-
121 level analyses in the complex song hierarchy. The current study aims to 1) to create an acoustic
122 dictionary of humpback song units for one population over multiple years, 2) extract a means of
123 quantifying similarity between those song units, 3) test the classification of sounds by the SOM
124 against qualitative classification using CART and RF analyses, and 4) use sequence analysis to
125 demonstrate the utility of applying both the acoustic dictionary and quantitative similarity
126 measures to new recordings.

127 **II. METHODS**

128 **A. Study Sites**

129 Data used in the current study were collected off the coast of Peregian Beach (26°30' S,
130 153°05' E), located on the Sunshine Coast in Queensland, Australia (Fig. 1a) as well as Point
131 Lookout (27°43' S, 153°53' E), located on North Stradbroke Island, Queensland, Australia (Fig.
132 1b). Both locations are along the migratory corridor of east Australian humpback whales where
133 the whales often swim within a few kilometers of the shoreline (Paterson and Paterson, 1984;
134 Noad and Cato, 2001).



135

136 **FIG. 1.** East Australia study sites: Peregian Beach and Point Lookout. The panel on the left
137 shows the placement of the hydrophone array (hydrophone buoys are numbered 1-5) and the
138 autonomous recorder deployments. The panel on the right shows the relative distance between
139 the two study sites.

140 **B. Data Collection**

141 Recordings from 2002-2014 were made using several platforms. A moored hydrophone
142 array consisting of five buoys was deployed off of Peregian Beach in 2002-2004, 2008-2011, and
143 2014 (Fig. 1a). Each buoy had a High Tech HTI-96-MIN hydrophone with a built-in pre-
144 amplifier (+40 dB), a customized amplifier (+20 dB), and a VHF radio transmitter (AN/SSQ-
145 47A). They were set up 1.5 -2.5 km from shore, spaced approximately 750 m apart at depths of
146 18-28 m. Buoy signals were received at an onshore base station using a four-channel type 8101
147 Sonobuoy VHF receiver (buoys 1-4), or a single channel Sonobuoy frequency converter
148 connected to a commercial FM radio receiver (buoy 5). Signals were digitized using a National
149 Instruments E-series data acquisition card and recorded to a desktop computer with *Ishmael*
150 acoustic software (Mellinger, 2001) at a sampling rate of 22 kHz, 16 bit depth, and stored as
151 multi-channel WAV files. These recordings were supplemented with boat-based recordings
152 using Cleavite CH17, GEC Marconi SH101X, or High Tech Inc. HTI-96-MIN hydrophones
153 connected to Sony DAT, Microtrack, or Zoom digital recorders (generally using 44.1 kHz
154 sampling rate, 16 bit depth, frequency response 30 Hz-20 kHz). Boat based recordings were the
155 sole source of data in 2005-2007.

156 Autonomous underwater acoustic recorders were placed off the coast of Peregian Beach
157 in 2012-2014. Each of the two recorders (Acousonde 3A with external battery housings,
158 Greenridge Sciences, www.acousonde.com) had a sampling rate of 25,818 Hz with a 9 kHz low
159 pass filter and a gain of 20 dB. Both Acousondes were placed in the same location,
160 approximately 1.5 km from the shoreline (Fig. 1a). Each was set on alternate 12 hour duty
161 cycles, resulting in essentially continuous recording for the duration of each deployment. All
162 recordings covered the frequency range of humpback whale song.

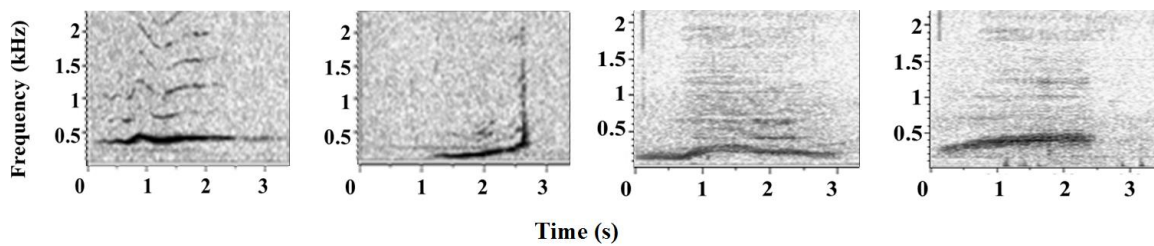
163 C. Measurement of Acoustic Features of Sound Units

164 Recordings of songs were visualized as spectrograms in Raven Pro 1.4
165 (www.birds.cornell.edu/raven) using a Fast Fourier Transforms with Hann window, and 90%
166 overlap. Good quality spectrograms were defined by a signal-to-noise ratio (SNR) of at least 10
167 dB above the background noise. Six complete song cycles from a singer in each year (2002-
168 2014) were selected for measurement. Themes, phrases, and units were identified based on the
169 accepted hierarchical structure of humpback whale song as described in Payne and McVay
170 (1971). The exception was 2007, in which only four song cycles were selected due to a lack of
171 available, high quality recordings. This resulted in 76 complete song cycles from 13 individuals
172 being selected for acoustic measurement. From each of the six song cycles in a given year, three
173 phrase repetitions of each theme were selected for measurement based on the highest quality
174 repetitions within the recording (high SNR). The aim of the current study was to create a set of
175 general representative sound types, and thus every atypical signal need not be represented. A
176 subsample of phrase repetitions addresses variability found within themes while preventing
177 overrepresentation of themes whose phrases are repeated with disproportionately high frequency.
178 Further, the three phrase repetitions were taken from the beginning, middle, and the end of the
179 theme to account for shifting themes that change subtly over multiple repetitions (Payne and
180 Payne, 1985). A total of 3720 phrases from the 76 complete song cycles were selected and
181 utilized for acoustic measurement.

182 Sound units were separated into two groups prior to measurement, contoured and non-
183 contoured, which have distinctly different feature profiles (Dunlop *et al.*, 2007; Murray *et al.*,
184 2016). Separate methods were used in order to measure the acoustic features of each sound type
185 in more detail (following Murray *et al.*, 2016). Contoured units have a definitive and traceable

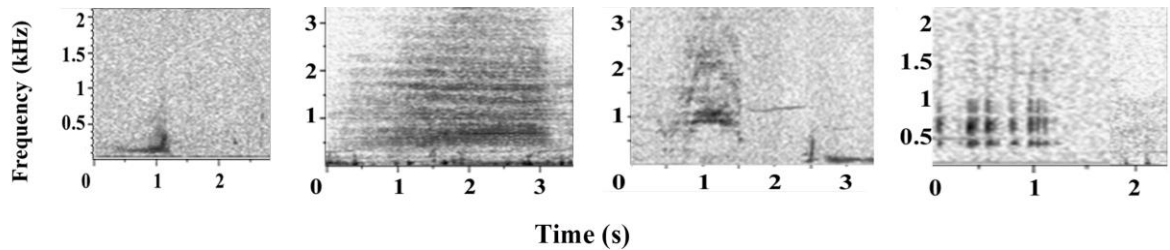
186 shape, such as tonal and harmonic units, as well as complex units containing both broadband and
 187 harmonic elements (see examples in Fig. 2a) (Dunlop *et al.*, 2007). Non-contoured units have no
 188 traceable shape or harmonic elements, such as purely broadband and pulsed calls (see examples
 189 in Fig. 2b). The decision to separate units allows for the use of contour tracing software, which
 190 provides multiple frequency measurements along the contour of a sound. This results in a more
 191 comprehensive representation of tonal and complex sounds by quantifying a signal's shape. A
 192 frequency contour cannot be generated for non-contoured units due to the lack of a traceable
 193 shape, necessitating the use of two different methods of measurement.

194



195 a)

196



197 b)

198 FIG. 2: Spectrogram examples of a subset of the a) contoured and b) non-contoured units. All
 199 spectrograms were generated in Raven Pro 1.4 using 2048 FFT, Hann window, 90% overlap.

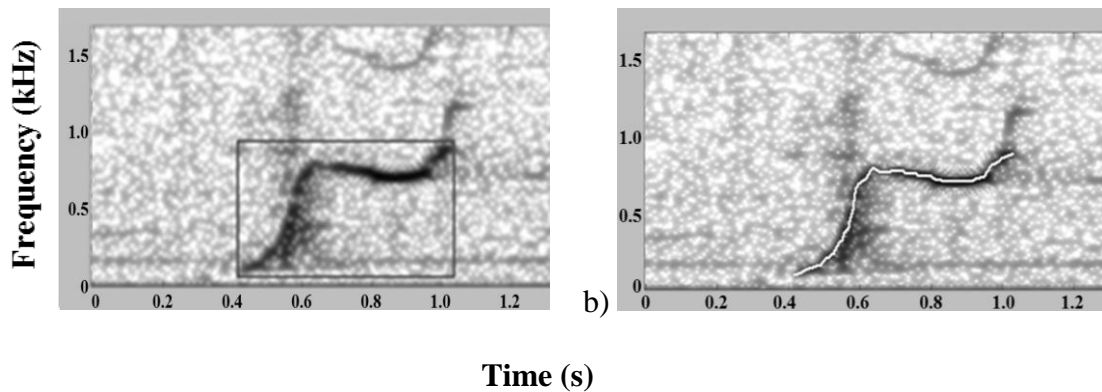
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201 1. *Contoured Feature Measurement*

202 Contoured sound units were measured using the frequency contour tracing program

203 *Beluga* (<http://biology.standrews.ac.uk/soundAnalysis/>), within *MATLAB 2014b* (The

204 MathWorks Inc, 2014). Recordings were imported into *Beluga* as WAV files. A spectrogram
205 was calculated using an FFT of 2048, frame length of 1024, 93.75% overlap between frames,
206 and Hanning window function. A tracing box was placed around the entire signal (Fig. 3a), and
207 the recording was filtered to remove the average noise spectrum. The frequency contour was
208 extracted using the “peaks” method without harmonics, measuring peak frequency every 0.03
209 seconds along the signal and creating a vector with a length analogous to the unit’s duration (Fig.
210 3b). SOMs require vectors of equal length; therefore, contour vectors were truncated by
211 extracting fifty equally spaced points along the vector. Each point was treated as a separate
212 variable, similar to the computations method of classification developed by McCowan (1995).
213



216 FIG. 3: Spectrogram example of the *Beluga* contour tracing method, showing a) the tracing box
217 around the signal and b) frequency contour trace

218

219 Additional measurements extracted from *Beluga* were: minimum frequency, maximum
220 frequency, start frequency, stop frequency, duration, trend, and bandwidth (see Table I for full
221 descriptions). Inflections, defined as changes in the slope of the frequency contour, were
222 counted based on the extracted contour of the sound (following Dunlop *et al.*, 2007). Pulse

223 repetition rate (PRR) was counted (per second) using the Raven spectrograms and corresponding
224 waveforms from which these units were originally transcribed.

225

226 **2. *Non-Contoured Feature Measurement***

227 Non-contoured units were measured using the robust measurements available in Raven
228 Pro 1.4 (Charif *et al.*, 2010). Recordings were imported into Raven as WAV files.

229 Spectrograms of recordings were loaded with an FFT of 2048, Hann window, and 90% overlap.

230 A tracing box was placed around units and the following features were extracted: duration,

231 center frequency, peak frequency, frequency 5%, frequency 95%, and bandwidth 90% (Table II).

232 Inflection and pulse repetition rate (PRR) were counted visually based on the spectrogram and
233 corresponding waveform.

234

235 **D. Creating a Self-Organizing Map**

236 Self-organizing maps (SOM) were created using the *selforgmap* function of the Neural
237 Network Toolbox in *MATLAB* 2014b. There were 59 acoustic features (9 variables and 50
238 frequency contour points) in the contoured input vectors, and 8 acoustic features in the non-
239 contoured input vectors. *Z*-scores were used to standardize the data in order to account for the
240 variety of different variable scales. Separate maps were created for the two types of signals due
241 to the different methods of acoustic feature measurement described above (following Murray *et*
242 *al.*, 2016). Map sizes that divide data too coarsely over-simplify differences, while dividing it
243 too finely creates categories with superfluous detail (Walker *et al.*, 1996; Céréghino and Park,
244 2009). Map dimensions were therefore determined using trial and error (Kohonen, 2014). Due
245 to the current study's aim of creating generalized sound types, 'lumping' signals into fewer

246 broad groups was favored over ‘splitting’ them into many smaller ones that would not represent
247 generalized categories (Mercado and Kuh, 1998). The resulting dimensions were a 10 x 10 map
248 (100 nodes) for contoured units and a 7 x 7 map (49 nodes) for non-contoured units. Once
249 dimensions were established, the SOM was trained and created using the dataset, with
250 neighborhood size and learning rate kept at the default MATLAB settings of 3 and 0.01
251 respectively (Demuth *et al.*, 2014). The chosen dimensions determined the number of nodes, or
252 groupings into which the data were placed. Each measured signal was placed into a single node.

253

254 **E. Comparison of SOM and Qualitative Classification**

255 Classification and Regression Tree (CART) (Breiman *et al.*, 1984) and Random Forest
256 (Breiman, 2001) analyses were used to assess the relative consistency between SOM and manual
257 classification techniques when given the same set of data and input variables. Prior to the
258 formation of the map, the measured sounds were also qualitatively assessed and classified by JA
259 resulting in 261 contoured sound types and 42 non-contoured sounds. Agreement between the
260 method of classification and the decision tree analyses were calculated for each classifying
261 technique separately. Contoured and non-contoured units also had to be evaluated separately due
262 to the differences in their acoustic variables. Multivariate PCA and DFA are commonly used
263 analysis methods for corroboration of qualitative data categorization, particularly for animal
264 vocalization (Boisseau, 2005; Dunlop *et al.*, 2007; Rekdahl *et al.*, 2013). However, CART
265 analysis addresses assumptions made by these analyses; data can be non-parametric, non-normal,
266 and have correlated variables (Van Opzeeland and Van Parijs, 2004; Melendez *et al.*, 2006;
267 Garland *et al.*, 2012; Rekdahl *et al.*, 2013). CART decision trees split data into branches based
268 on the Gini Index, a commonly used measure of “goodness of split” which reduces heterogeneity

269 within the groups (Breiman *et al.*, 1984). At each split of the tree, all possible divisions to the
270 data (by variable) are considered. This allows division of data to be based on a different splitting
271 criterion at each branch (e.g., is start frequency > 500 Hz). The criterion chosen represents the
272 highest reduction in heterogeneity in the data (Karels *et al.*, 2004). CART was implemented here
273 with cross-validation using the *rpart* package in R (Therneau *et al.*, 2014), with each terminal
274 branch of the CART (analogous to a node or a category) set to a minimum size of 10 (Table III).
275 Each of the resulting decision trees were pruned to prevent overfitting of the data using the 1-
276 standard deviation rule (see Breiman *et al.*, 1984). CART provides information on the ability of
277 the analysis to classify calls (root node error) and also the agreement in classification between
278 CART and the classification technique it is evaluating.

279 Random Forest is a more robust expansion of CART, where a forest of CART trees is
280 created to allow an internal estimate of uncertainty. By applying a bootstrapping technique
281 known as ‘tree bagging’ to the process of creating decision trees, Random Forests can randomly
282 sample combinations of the variables available to produce the lowest out-of-bag (OOB) error
283 rate. This allows an estimate of classification error per call type and the overall OOB error rate
284 of the forest, from which classification agreement can be determined. Random Forest was
285 implemented here using the *randomForest* package in R (Table III) (Liaw and Wiener, 2002),
286 with 1000 trees grown for each forest and the predictor variables that were randomly selected set
287 to 3. The Gini Index was also used here to indicate the importance of each of the predictor
288 variables. Gini values indicate order of relative variable importance in the splitting decisions and
289 are not directly comparable across separate analyses.

290 CART and Random Forest analyses were each used to evaluate the two classification
291 techniques: 1) manual, or qualitative description (**Q**), and 2) SOM node placement (**SOM**).

292 Contoured (**C**) and non-contoured (**NC**) units were analyzed separately given that they were
293 measured differently. The dataset of contoured units was classified independently by both the
294 SOM (**C-SOM**) and qualitatively (**C-Q**). The dataset of non-contoured units was also classified
295 by both the SOM (**NC-SOM**) and qualitatively (**NC-Q**). Each of the four classifications was
296 treated as a separate subset of the data. Each subset was evaluated separately for classification
297 agreement with a CART analysis, as well as with a Random Forest analysis, for a total of eight
298 analyses. A non-parametric Mann-Whitney/Wilcoxon test was used to compare the degree of
299 classification agreement found for each method.

300

301 **F. Utilizing SOM Cartesian distances to quantify song similarity**

302 To quantify the relative acoustic similarities between prototype units, the distance
303 between the nodes was measured on the Cartesian plane as arranged by the SOM spatial layouts
304 (Fig. 4). Each SOM was placed on a two-dimensional plane and every node was assigned an
305 (X,Y) coordinate with all adjacent nodes having a distance of 1. Based on these coordinates, a
306 matrix was generated of all the relative Cartesian distances between the nodes in the SOM
307 layout. This matrix provided a quantitative measurement of relative similarity among unit types
308 based on their spatial arrangement in the SOM.

309 To demonstrate the utility of SOMs in combination with the similarity weightings, song
310 cycles from the East Australian population in 2008 were transcribed following the prototype
311 units generated from the SOM classification as a guide. Qualitatively identified themes within
312 the 2008 song were then validated using Levenshtein distance analysis of the phrase repetitions
313 transcribed using the SOM classifications. The Levenshtein distance is a similarity measurement
314 that calculates the minimum number of insertions, deletions, and substitutions needed to convert

315 one string of data into another. This score can then be normalized to account for differences in
316 string length, creating an index of similarity known as the Levenshtein distance similarity index
317 (LSI) (Helweg *et al.*, 1998; Garland *et al.*, 2012; Murray *et al.*, 2016). Here, a weighted LSI
318 analysis was implemented where the cost matrix for substituting units was based on the matrix of
319 Cartesian distances extracted from the SOM, exponentially scaled between 0 and 1. This
320 allowed the cost of substituting similar units to be a direct measure of acoustic similarity and the
321 cost of insertions or deletions remained as cost=1 (see Garland *et al.* (2017) for detailed
322 methodology and rationale). In essence, substitutions between highly similar units were
323 considered to be less costly (based on SOM distances), while insertions, deletions, and
324 substitution of units from separate maps were assigned a maximum penalty of cost=1. If themes
325 that were qualitatively identified within the 2008 song could also be identified through the
326 Levenshtein Distance analysis, it would demonstrate the repeatability of the transcriptions made
327 using the acoustic dictionary. Average-linkage hierarchical cluster analysis and bootstrapping
328 (using *pvclust* and *bootstrap* in *R*) were run to assess the similarity between all data strings. The
329 cophenetic correlation coefficient (CCC) was also calculated as a measure of how accurately the
330 above analyses represented the true similarity associations within the data, with a CCC>0.8
331 indicating a good representation of the data (Sokal and Rohlf, 1962).

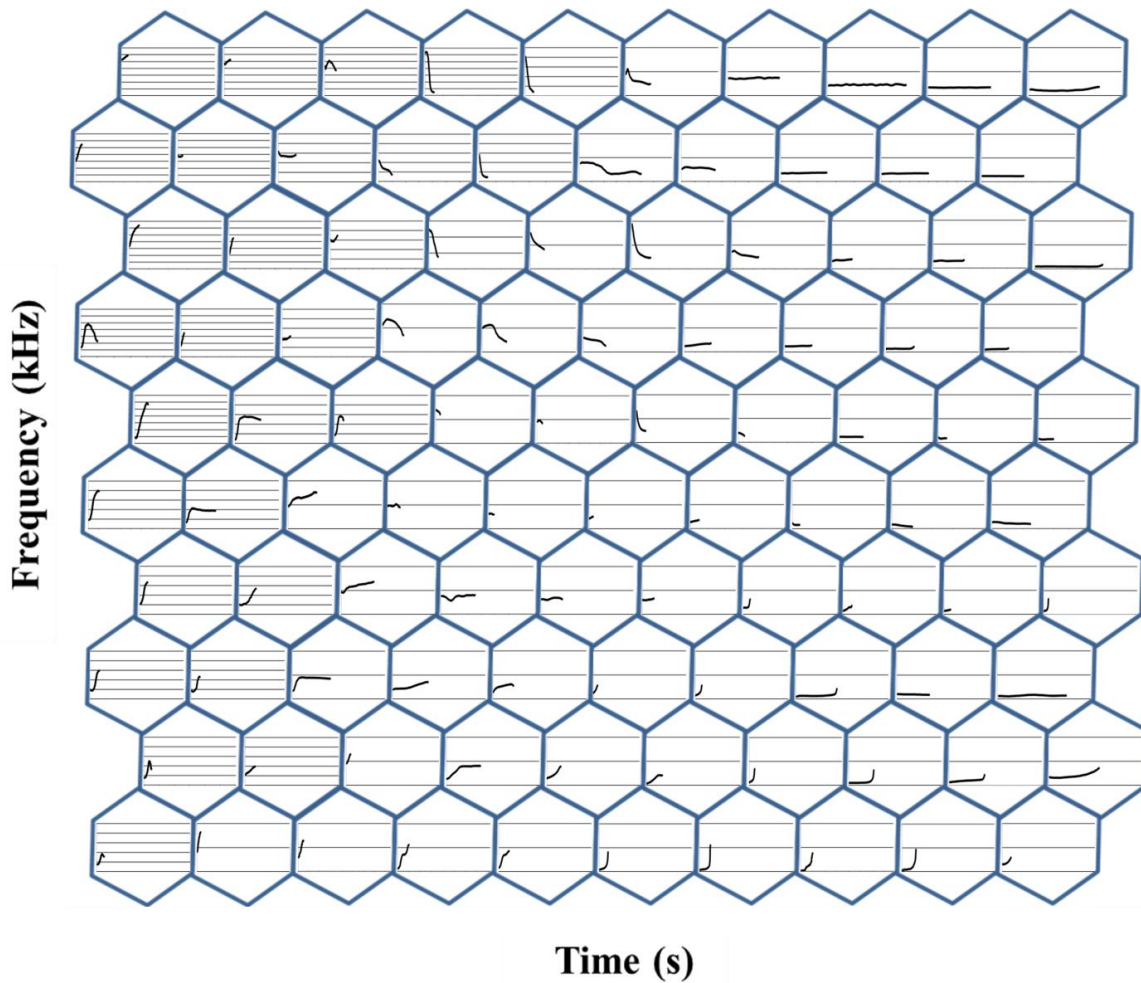
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333 III. RESULTS

334 A. Creation of Prototype Units

335 From 76 song cycles and 3720 phrases, 6409 sound units were measured and placed in
336 149 SOM nodes, 100 nodes within a 10x10 contoured SOM and 49 nodes within a 7x7 non-
337 contoured SOM. For each node, the average of each acoustic feature was calculated using all of

338 the units placed in that particular node, creating feature vectors for a set of prototype units
339 (Supplementary Materials, Table VI and VII). For the contoured SOM, each of the 50 frequency
340 contour points within a node was averaged and graphed, creating a visual representation of the
341 prototype unit for each node (Fig. 4). A visual representation of the non-contoured prototype
342 units was not possible because there was no frequency contours to extract. Nodes were
343 numbered from left to right, starting from the upper left node and ending with the lower right
344 node. Prototype units were numbered 1-100 for contoured units based on their SOM node
345 position, and from 101-149 for the non-contoured units. These units comprise an acoustic
346 dictionary of sound units which represents the song repertoire from 2002-2014 for the East
347 Australian humpback whale population.



348

349 FIG. 4. Visual representations of prototypical unit contours generated from the contoured unit
 350 10 x 10 SOM, based on the 50 frequency contour points extracted using Beluga. All visual
 351 representations have time on the x-axis (5 seconds for all nodes) and frequency on the y-axis
 352 (gridlines represents one kilohertz intervals). Adjacent nodes are more similar to each other than
 353 those that are not adjacent.

354

355 **B. CART Analyses**

356 For each of the CART analyses, a proportion of variables provided a root node error.

357 This resulted in an agreement of classification between the classification technique (either

358 qualitative or SOM) and the CART analysis. A summary of the classification agreements for
359 each analysis can be found in Table III. The top five variables used by the analyses and their
360 respective Gini Index values in each analysis can be found in Table IV.

361 **C. Random Forest Analyses**

362 For each of the Random Forest analyses, agreement in classification between the
363 classification technique (either qualitative or SOM) and the Random Forest analysis was
364 reported, as well as the most important variables as assessed by the Gini Index. A summary of
365 classification agreements for each analysis can be found in Table III. The top five variables used
366 by the analyses and their respective Gini Index values in each analysis can be found in Table V.

367

368 **D. Comparison of SOM and Qualitative Classification**

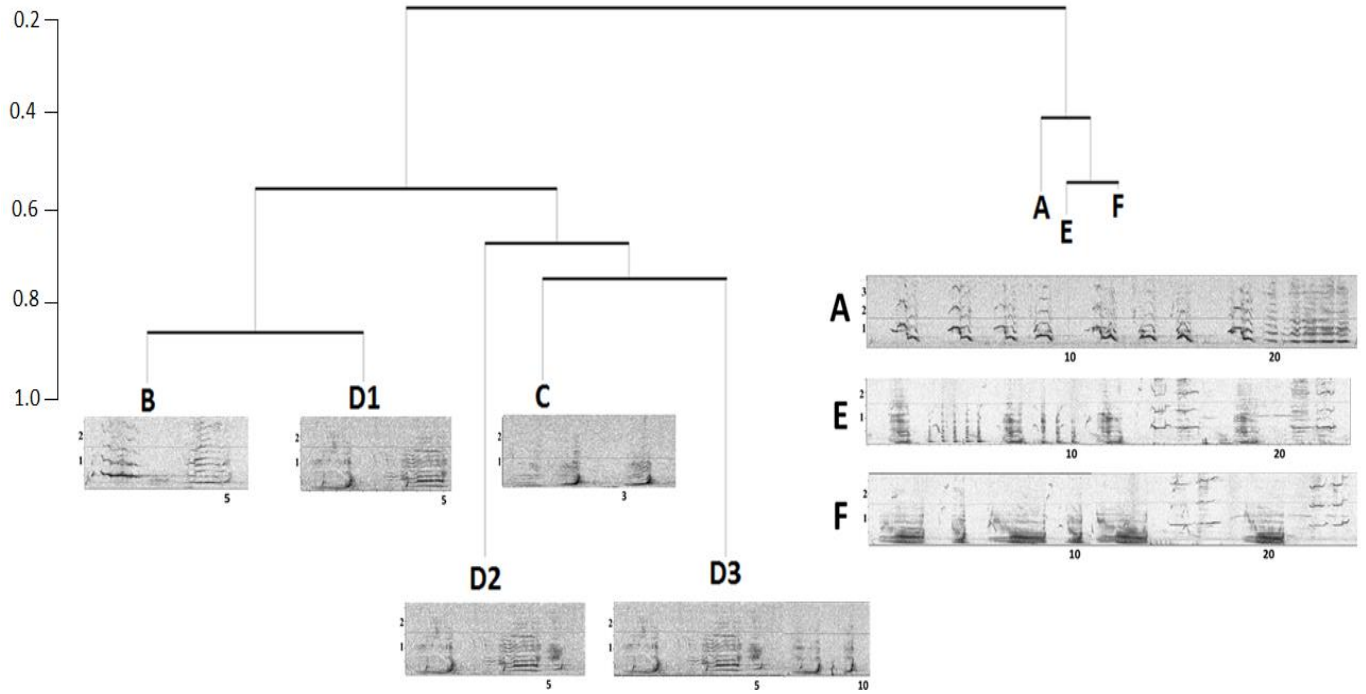
369 Results of the comparison between SOM and qualitative classifications are summarized
370 in Table III. Classification agreement with the CART analysis was found to be significantly
371 higher with the SOM technique (73%) as compared to the manual method (58%; Mann-
372 Whitney/Wilcoxon, $W=4770.7$, $p<0.01$) for contoured units, but there was no significant
373 difference in non-contoured units (Mann-Whitney/Wilcoxon, $W=918$, $p=0.48$). Classification
374 agreement with the Random Forest analysis was found to be significantly higher with the SOM
375 technique for both contoured (89% vs 73%; Mann-Whitney/Wilcoxon, $W=3987.5$, $p<0.01$) and
376 non-contoured units (91% vs 83%; Mann-Whitney/Wilcoxon, $W=685$, $p<0.01$).

377 **E. Utilizing the SOM prototypes and Cartesian distances to quantify song similarity**

378 Using the SOM classifications, 36 complete song cycles of the 2008 song were
379 transcribed from nine singers, comprising 7847 sound units arranged into 1864 phrases. No song
380 cycles measured for the original SOM analyses were used in this analysis to ensure independent

381 sampling. A dendrogram was generated based on LSI values using both hierarchical cluster
382 analysis and bootstrapping to display similarity between phrases (Fig. 5). The cophenetic
383 correlation coefficient (CCC) of 0.97 verified that the dendrogram was a very good
384 representation of the associations within the dataset. Most phrase repetitions of a given
385 qualitatively-identified theme were clustered together on the same major branch: therefore, each
386 major branch represented a different theme. The exception was Theme D, which contained three
387 phrase variants based on different phrase lengths (D1: two units, D2: three units, and D3: five
388 units). A qualitative examination of these variants (Fig. 5) showed that all three variants
389 contained the same two starting units. For example, to create D2, the three-unit variant, one unit
390 was inserted at the end of D1, the two-unit sequence. To create D3, the five-unit variant, two
391 additional units were inserted to the end of D2 (the three-unit sequence). Differences in length
392 are reflected in the LSI analysis, as insertions and deletions which lengthen or shorten a string
393 were more heavily penalized in this weighted LSI framework than substitutions (Garland *et al.*,
394 2017).

395



396

397 FIG. 5: Average-linkage hierarchically bootstrapped dendrogram of the East Australian 2008
 398 song based on the Levenshtein Similarity Index (LSI), which was weighted for substitutions
 399 using the Cartesian distances between units in the SOM. Horizontal lines correspond to the
 400 proportion of similarity, shown on the y-axis, between two branches. Each letter represents a
 401 qualitatively identified theme. Phrase repetitions of every theme, with the exception of Theme
 402 D, were clustered onto separate major branches. Spectrogram figures provide a visual
 403 representation of each theme, with time (s) on the x-axis and frequency (kHz) on the y-axis.
 404 Note that only major branches are shown; terminal branches representing individual phrase
 405 repetitions were excluded for clarity.

406

407 IV. DISCUSSION

408 SOM classification enabled the creation of an acoustic dictionary of prototypical units,
 409 which represents the repertoire of the east Australian humpback whale population's songs from
 410 2002-2014. The Cartesian distances between those units, a valuable product of the SOM

411 classification, provided a means of quantifying the similarity between all units across the entire
412 dictionary, which can be utilized in higher-level sequence analyses (Garland *et al.* (2017). This
413 dictionary can serve as a guide by which vocal sequences from new recordings can be manually
414 transcribed in a rapid, repeatable, and efficient manner. While prototypical units have been
415 created to represent humpback whale song before (Walker *et al.*, 1996; Mercado and Kuh, 1998),
416 small sample size in many of these studies limited their ability to be representative of an entire
417 repertoire over multiple years. Furthermore, none quantified the acoustic similarities between
418 their units. Cartesian distances as unit similarity weightings were instrumental to the
419 repeatability of the dictionary's application to a dataset. There will inevitably be variation in
420 signal classification for manual transcriptions for sequences. Quantifying similarity across units
421 allowed the Levenshtein Distance analysis to identify and cluster repetitions of a specific theme
422 despite those variations. The splitting of one theme's variations onto several branches based on
423 length and unit types reveals the important role that qualitative judgment still plays in the
424 classification and analysis of sequences. Ultimately a dictionary can minimize the amount of
425 work needed to analyze large volumes of data; it requires only a relatively small subset of
426 acoustic signals to be individually measured. Given that acoustic databases can contain hundreds
427 of hours of recordings, comprehensive analyses can be difficult if every unit must be measured.
428 Measuring a representative subsample to create a dictionary should increase the sample size of
429 recordings that could ultimately be used for further analysis in many types of vocalization
430 studies.

431 Precedence exists for SOM signal classification in a number of species, and it has some
432 advantages over the manual technique. Although entirely automatic techniques would be the
433 most objective, vocal signals often have too much variation for these to be effective (Janik,

434 1999). SOM classification eliminates one of the many qualitative steps within the study of
435 vocalizations by placing signals into categories through quantitative and repeatable means. Map
436 size is subjectively derived, but an advantage of this is that it allows for flexibility in studies of
437 vocalizations at different resolutions. Small maps can be used for broad-scale contexts like
438 territories or inter-population variation, while larger maps can be used for fine-scale detail such
439 as individual variation. When implementing the dictionary on new, unmeasured recordings, the
440 prototype unit that is ultimately selected as the best match for a signal is still manually decided.
441 The similarity weightings derived from the SOM account for the variations in manual
442 classification that occur due to subtle differences or similarities in unit types that may be
443 identified by the human observer.

444 CART and Random Forest analyses provided a quantitative means of directly comparing
445 between SOM and manual classification techniques. Both analyses found significantly higher
446 classification agreement when contoured units were classified by the SOM method as compared
447 to being classified manually. While Random Forest also found significantly higher agreement
448 when non-contoured units were classified by the SOM, there was no significant difference in
449 classification agreement when non-contoured units were classified either SOM or manually.
450 This implies that the SOM method is more effective for contoured sounds. Acoustic
451 characteristics can impact which technique might be better suited to each signal type. Subtle
452 differences in the contour of tonal sounds may be obscured to a human observer, particularly in
453 cases of repetitive sequences with gradually changing units. Conversely, acoustic measurements
454 of non-contoured units may not necessarily create a comprehensive description of the signal. It
455 should be noted, however, that biological relevance of these differences in either signal type is
456 unclear. A disadvantage of the SOM is that human observers can often detect nuanced

457 differences not captured by measurement alone, which is why automatic classification has
458 typically been less accurate (Janik, 1999). This could explain why CART found the SOM and
459 manual techniques to be equivalent for non-contoured units. Manual classification has the
460 advantage of recognizing and addressing these nuanced differences, while SOM has the
461 advantage of being a more repeatable and robust approach.

462 The methods described here are only applicable to high-quality recordings from which
463 acoustic features can be measured accurately. The subset of recordings measured must also be
464 representative of the dataset under analysis. Additionally, the use of a single singer in each year
465 does not consider individual variations. This represents a limitation of the method as applied to
466 this dataset, and should be taken into account whenever appropriate during use in future studies.
467 Using data that fit the described criteria, acoustic similarity and structure of vocal signals can be
468 quantified for any number of vocal databases. Furthermore, an acoustic dictionary could also be
469 generated for these databases, filling a current gap in the body of knowledge (Placer *et al.*, 2006;
470 Kaufman *et al.*, 2012). This dictionary could then be used as a guide to transcribe sequences in
471 new recordings from the respective population or database. Quantifiable similarity between
472 these prototypical units can enhance the repeatability of the dictionary's application when used
473 in subsequent sequential analyses. While this method by no means eliminates the limitations of
474 the traditional approaches to acoustic signal categorization and analysis, it does provide a key
475 step in the process towards a more quantitative, robust, and repeatable approach.

476

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490

491 ***See supplementary material at [URL will be inserted by AIP] for Tables VI and VII,**
492 **which provide the averages for each of the acoustic feature variables used in the 10x10**
493 **contoured SOM (Table VI) and the 7x7 non-contoured SOM (Table VII).**

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608 Edinburgh), pp. 1-12.

609

610

611 **VI. TABLES**

612

613 TABLE I. Acoustic features measured for contoured units in *Beluga*.

| Acoustic Feature | Definition |
|-----------------------------------|--|
| Max frequency (Hz) | Highest peak frequency extracted from the frequency contour |
| Min frequency (Hz) | Lowest peak frequency extracted from the frequency contour |
| Start frequency (Hz) | The first peak frequency extracted from the frequency contour |
| End frequency (Hz) | The last peak frequency extracted from the frequency contour |
| Trend | Start frequency/end frequency. Values >1 indicate a sound that decreases in frequency, while values <1 indicate a sound that increases in frequency |
| Duration (s) | Length of the unit based on the extracted frequency contour |
| Bandwidth (Hz) | Maximum frequency – minimum frequency |
| Inflection | Number of changes in the slope of the frequency contour |
| Pulse repetition rate (/s) | The number of pulses in sounds that are contoured but have a pulsative element |
| Contour point (x50) (Hz) | Subsamples of the peak frequency measurements taken every 0.03 seconds to create the frequency contour. 50 samples were taken, evenly spaced along the frequency contour. Each subsample was treated as its own acoustic feature |

614

615

616 TABLE II. Acoustic features of non-contoured units measured using robust measurements in

617 *Raven*

| Acoustic Feature | Definition |
|-----------------------------------|--|
| Center frequency (Hz) | Frequency at which the sound is divided into two intervals of equal energy |
| Peak frequency (Hz) | Frequency at which the sound has maximum amplitude. |
| Frequency 5% (Hz) | Frequency at which the sound is divided into intervals containing 5% and 95% of its energy |
| Frequency 95% (Hz) | Frequency at which the sound is divided into intervals containing 95% and 5% of its energy |
| Duration (s) | Length of the unit based on the spectrogram visualization |
| Bandwidth 90% (Hz) | Frequency 95% - Frequency 5% |
| Inflection | Number of changes in the slope of the frequency contour |
| Pulse repetition rate (/s) | Number of pulses in sounds that have a pulsative element |

618

619 TABLE III. Classification agreements between method of classification and decision tree
 620 analysis (both CART and Random Forest) used to evaluate classification techniques. Root node
 621 errors, determined for CART only, represents the percentage of classification of call types.
 622 Significantly higher agreements based on Mann-Whitney/Wilcoxon tests are shown in bold.

| Corroborating Method | Unit Types | Qualitative Agreement | SOM Agreement |
|-----------------------------|-------------------|------------------------------------|---|
| CART | Contoured | 57.55% (95.02% root node error) | 73.03% (95.35% root node error) |
| CART | Non-contoured | 78.97% (93.20% root node error) | 74.24% (81.11% root node error) |
| Random Forest | Contoured | 73.01% | 89.21% |
| Random Forest | Non-contoured | 83.31% | 90.93% |

623

624 TABLE IV. Variables used in the CART analyses and mean decrease in Gini index. C-SOM =
 625 contoured units classified by SOM, C-Q = contoured units classified by qualitative naming, NC-
 626 SOM = non-contoured units classified by SOM, NC-Q = non-contoured units classified by
 627 qualitative naming.

| C-SOM | | CART | | | | NC-Q | |
|------------------|-------------|------------------|-------------|------------------|-------------|------------------|-------------|
| Variables | Gini | C-Q | Gini | NC-SOM | Gini | Variables | Gini |
| | | Variables | | Variables | | | |
| Duration | 823 | Duration | 630 | Freq. 95% | 578 | Duration | 597 |
| Trend | 628 | Trend | 360 | Bandwidth 90% | 553 | Center | 439 |
| Inflection | 622 | Start | 344 | Freq. 5% | 434 | Freq. 95% | 413 |
| End | 469 | Inflection | 326 | Center | 418 | Peak | 410 |
| Max | 443 | Contour Point 2 | 319 | Peak | 392 | Freq. 5% | 373 |

628

629

630 TABLE V. Variables used in the Random Forest analyses and mean decreasing Gini index. C-
 631 SOM = contoured units classified by SOM, C-Q = contoured units classified by qualitative
 632 naming, NC-SOM = non-contoured units classified by SOM, NC-Q = non-contoured units
 633 classified by qualitative naming.

634

| <i>RANDOM FOREST</i> | | | | | | | |
|----------------------|-------------|------------------|-------------|------------------|-------------|------------------|-------------|
| C-SOM | | C-Q | | NC-SOM | | NC-Q | |
| Variables | Gini | Variables | Gini | Variables | Gini | Variables | Gini |
| Duration | 805 | Duration | 821 | Bandwidth 90% | 330 | Duration | 416 |
| Inflection | 595 | Trend | 477 | Freq. 95% | 241 | PRR | 210 |
| Trend | 559 | Inflection | 342 | PRR | 224 | Peak | 197 |
| Max | 221 | Max | 188 | Freq. 5% | 218 | Center | 186 |
| PRR | 207 | Bandwidth | 179 | Duration | 217 | Freq. 95% | 155 |

635